

Portable Test and Stimulus: The Next Level of Verification Productivity is Here

Part 1

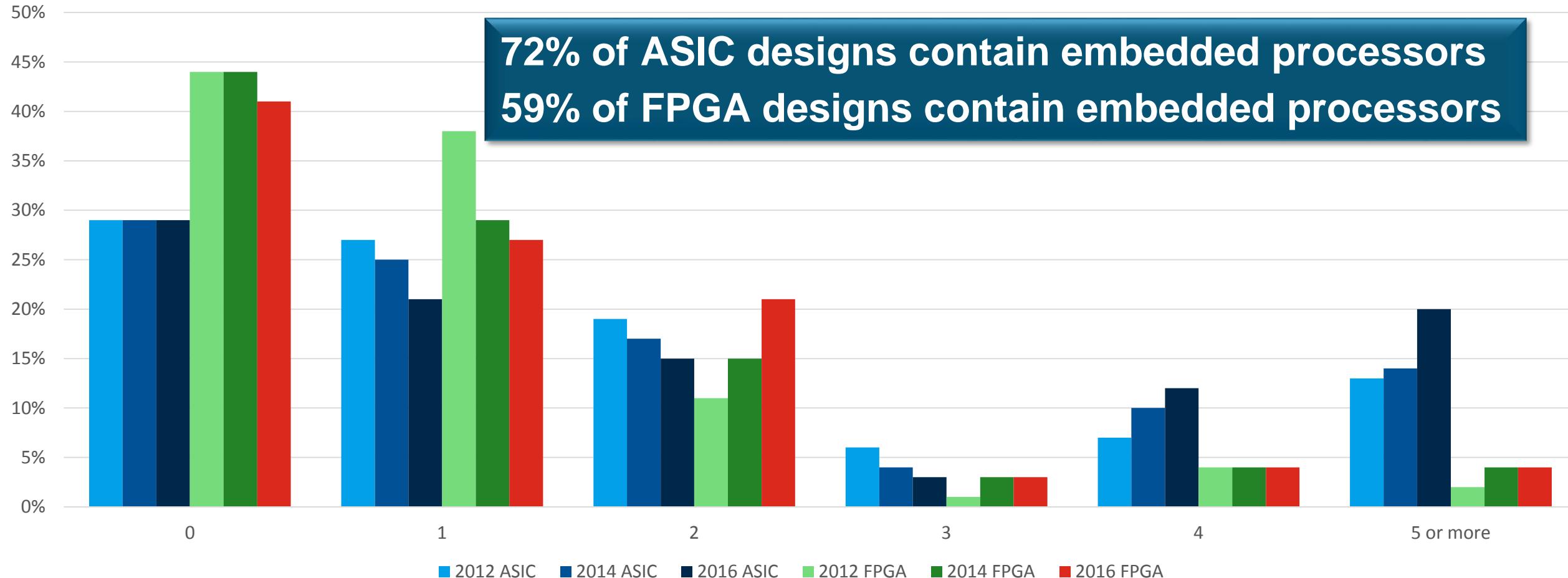
Accellera Portable Stimulus Working Group

2/26/2018

It's an SOC World

Number of Embedded Processor Cores

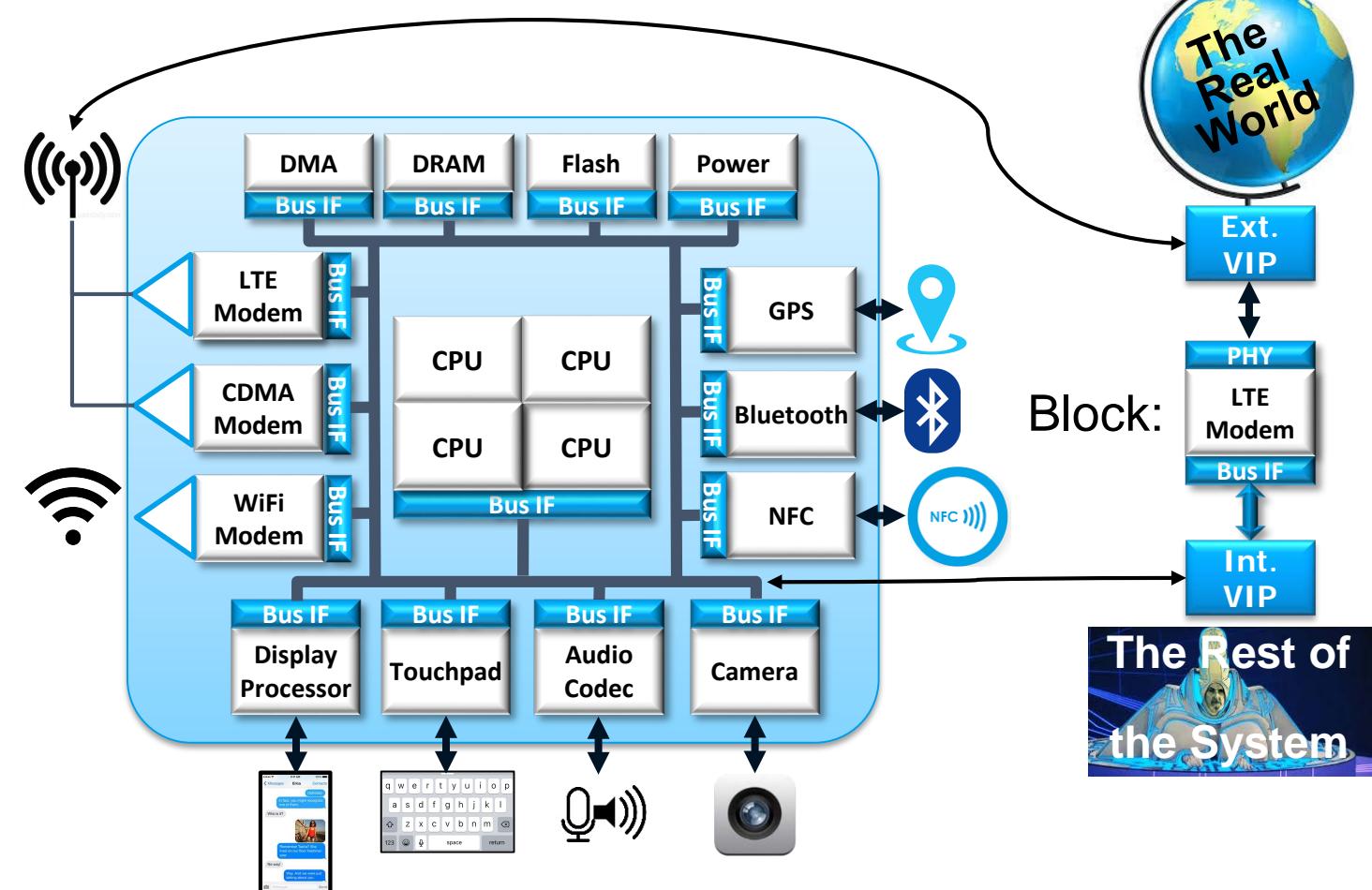
72% of ASIC designs contain embedded processors
59% of FPGA designs contain embedded processors



Source: Wilson Research Group and Mentor Graphics, 2016 Functional Verification Study

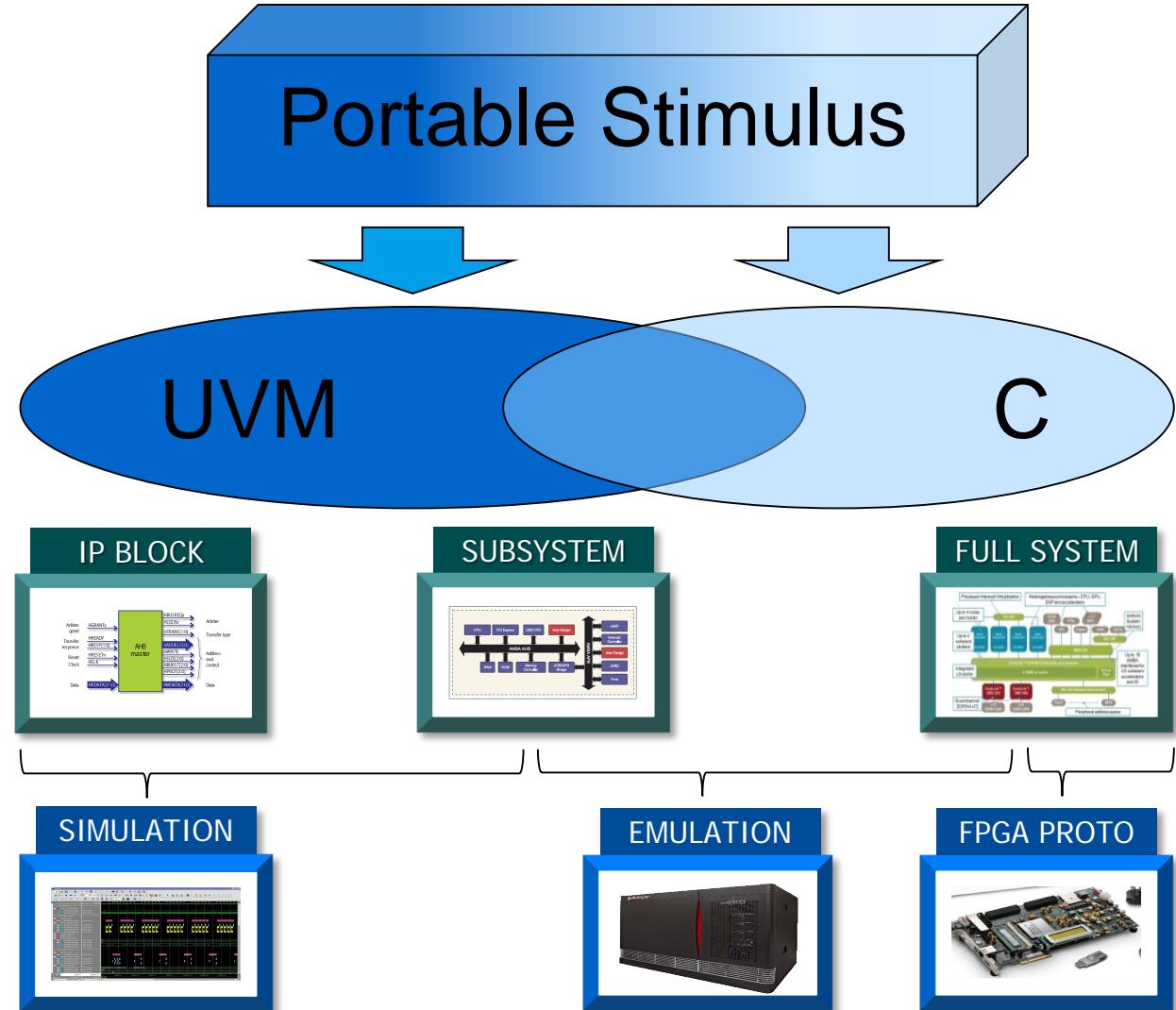
Block-to-System Test Reuse

- UVM constrained-random is great for block-level testing
 - UVM Sequences model both external & internal behavior
 - Block tested standalone
- SOC-level tests driven by use-cases
 - Embedded SW drives the test
 - Usually written in C
- Still want to test the block
 - Need to reuse *test intent*
 - Coordinate with other traffic

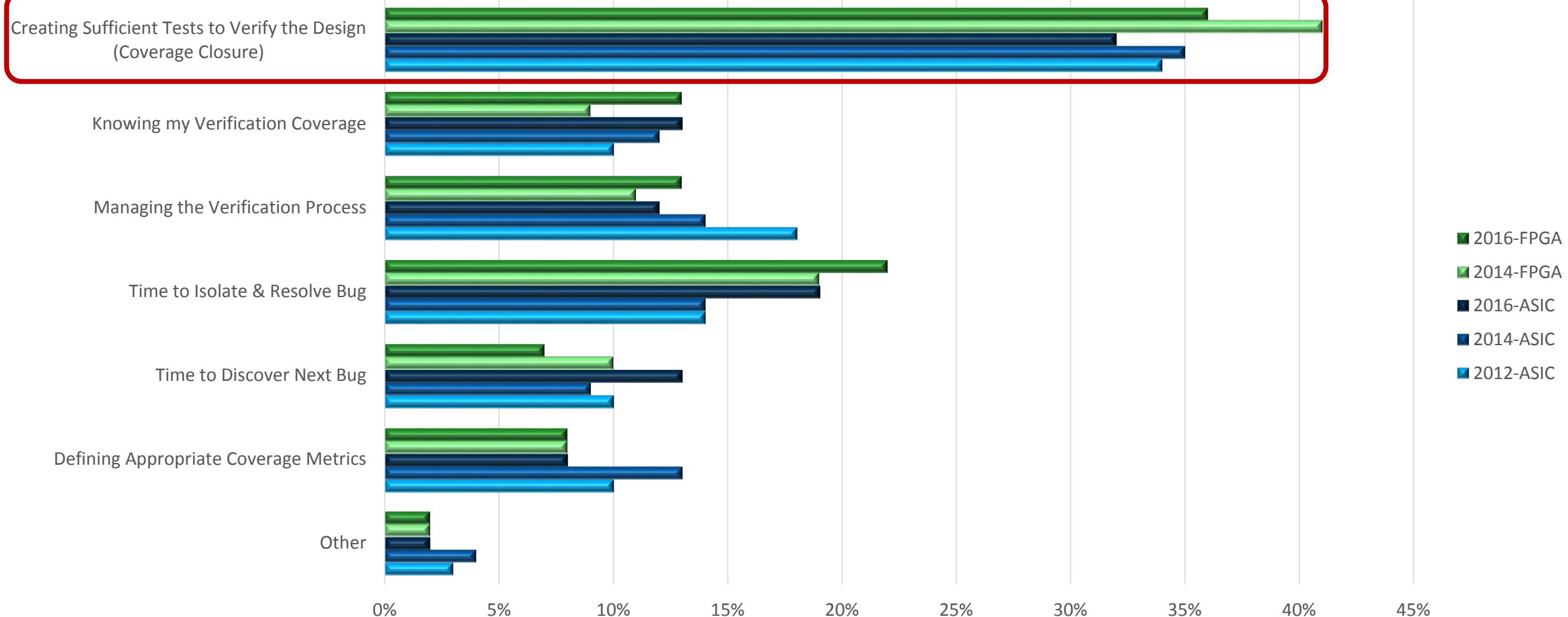


Reuse of Test Intent Across Platforms/Users

- Single specification of test intent is critical
- Define "scenario space" by capturing:
 - interactions
 - dependencies
 - resource contention
- Abstraction lets tool automate generation
 - Multiple targets
 - Target-specific customization



Biggest Verification Challenges



Source: Wilson Research Group and Mentor Graphics, 2016 Functional Verification Study

Maximize Productivity by Separating Concerns

Directed:

```
start(Boston);
drive(West, I90, Buffalo);
if(!Canada)
    drive(West, I90, Chicago);
    drive(West, I80, Salt Lake City);
    drive(West, I84, Portland);
else
    drive(North, I190, Niagra Falls);
    drive(West, ON403, Flint);
    drive(North, I75, Fargo);
    drive(West, I94, Billings);
    drive(West, I90, Ritzville);
    drive(South, US395, Stanfield);
    drive(West I84, Portl)
```



How do we adjust the scenarios?

Maximize Productivity by Separating Concerns

Constrained-Random:

```
class drive;
    rand city_e start, end;
    rand dir_e direction;
endclass
```

```
class directions;
task body;
    drive.go() with {start == Boston,
                     dir == West;}
    while(drive.end != Portland)
        drive.go();
endtask
```

```
constraint NoCanada{
    start==Buffalo -> dir == West;}
constraint Chi {
    start==Chicago -> dir == West;}
...
endclass
```



```
class drop_friend extends directions;
    constraint Chi {start==Chicago -> dir inside [North, West];
                    start==Chicago -> end==Minneapolis;}
```

endclass

```
class sightsee extends drop_friend;
```

```
constraint DT {start==Minneapolis -> end==DevilsTower;}
```

```
constraint MR {start==DevilsTower -> end==MountRushmore;}
```

```
constraint MT {start==MtRushmore -> end==Boston;}
```

endclass

**Testwriter must still manage details
 Global Optimization is Difficult**

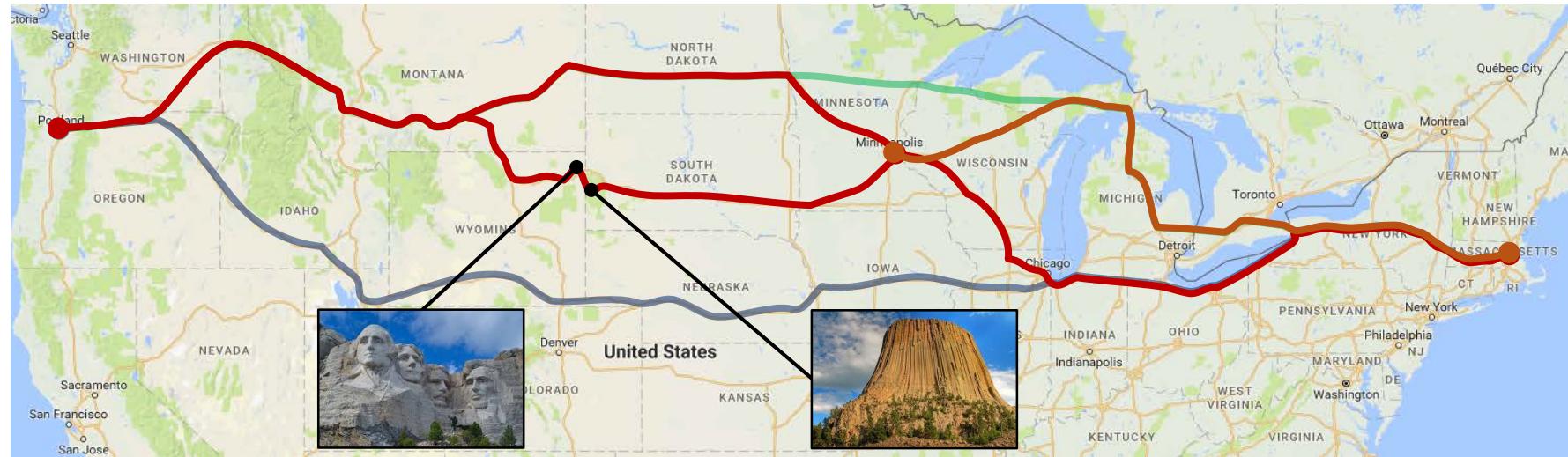
Maximize Productivity by Separating Concerns

Declarative:

```
start == Boston;  
end == Portland;
```

```
set_point(Minneapolis);  
set_point(MtRushmore);  
set_point(DevilsTower);  
set_preference(West);
```

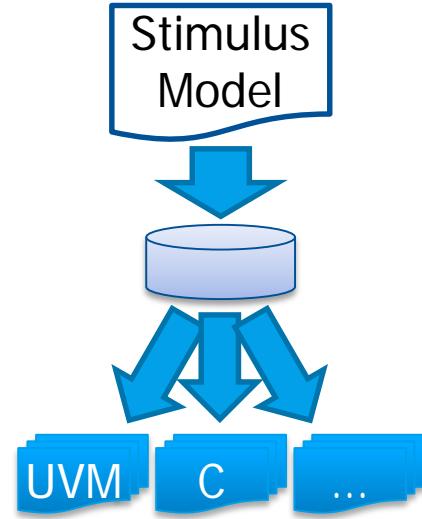
...



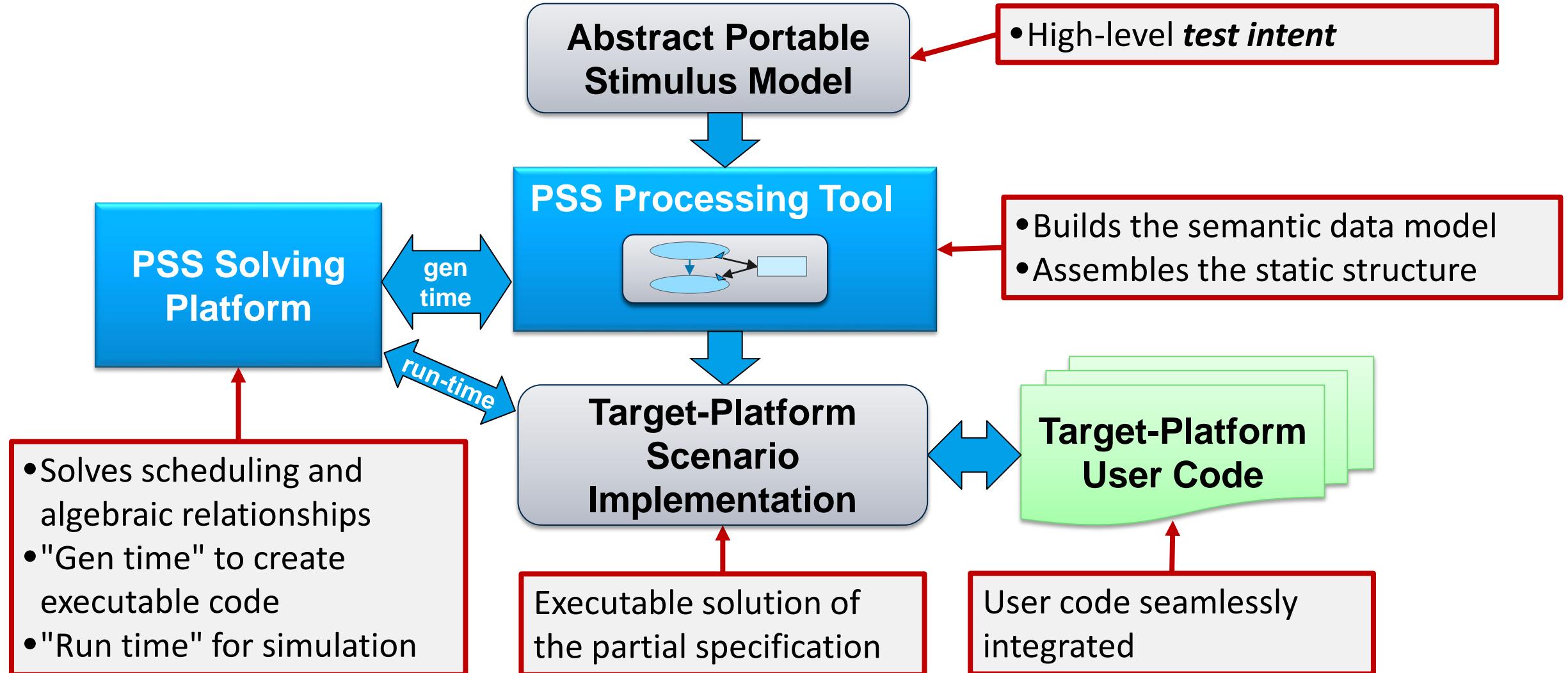
Testwriter focuses on INTENT
Tools handle the details

Modeling Portable Stimulus Requires Abstraction

- Begin with the end in mind
 - Translating one language into another is hard
 - Each target language has its own semantics
- Abstraction lets us focus on common semantics
 - Schedule well-defined behaviors
 - Scheduling semantics allow scenario exploration
- Single partial specification expanded into multiple scenarios



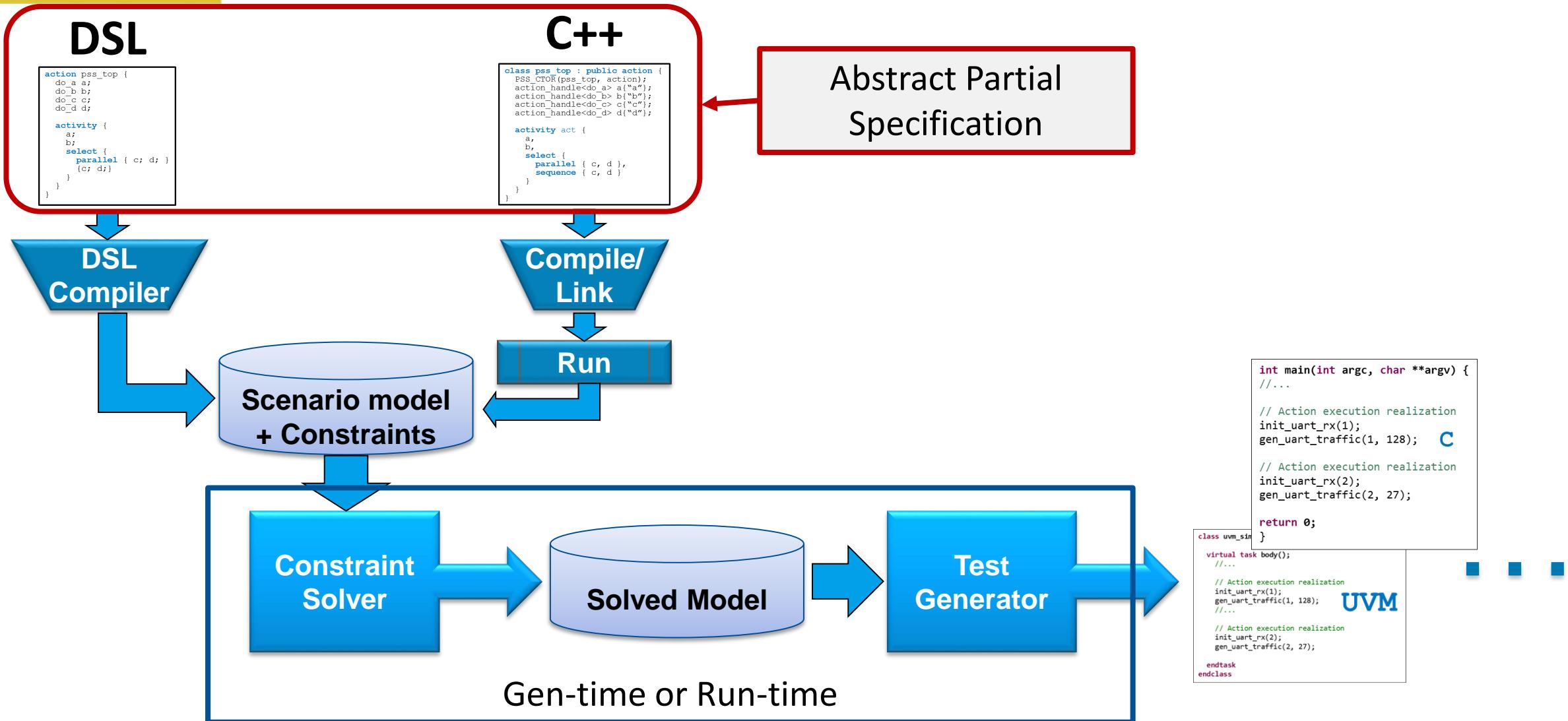
So, How Is This All Going to Work?



What Portable Stimulus Is NOT

- **NOT** a UVM replacement
- **NOT** a reference implementation
- **NOT** one forced level of abstraction
 - Expressing intent from different perspectives is a primary goal
- **NOT** Monolithic
 - Representations would typically be composed of portable parts
- **NOT** Two standards
 - PSS/DSL and PSS/C++ input formats describe 1:1 semantics
 - Tools shall consume both formats
- **NOT** Just stimulus
 - Models Verification Intent
 - Stimulus, checks, coverage, scenario-level constraints
 - Portable test realization

Projected Tool Flow



Hello, World

Hello World: Atomic Actions

hello
world

component groups elements
for reuse and composition

action defines behavior

exec defines implementation

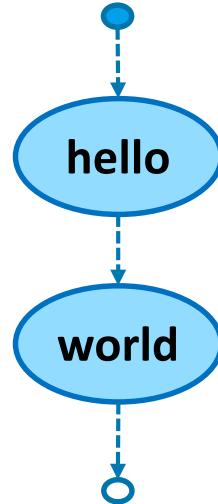
```
component pss_top {
    action hello_world_a{
        exec body SV = """
            $display( "Hello World" );
        """ ;
    }
}
```

```
class hello_world_a_seq_1 extends uvm_sequence;
    `uvm_object_utils(hello_world_a_seq_1)

    virtual task body();
        $display( "Hello World" );
    endtask
endclass
```

- ✓ Reuse
- ✓ Composition
- ✓ Abstract behaviors
- ✓ Retargetable Implementations

Hello World: Compound Actions



compound action
 traverses other actions

activity
 defines scheduling

```

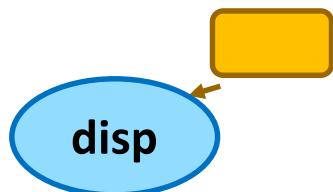
void hello_world_a_test_1() {
    printf( "Hello\n" );
    printf( "World\n" );
}
    
```

```

component pss_top {
    action hello_a {
        exec body C = """
            printf("Hello\n");
            """
        }
    }
    action world_a {
        exec body C = """
            printf("World\n");
            """
        }
    }
    
```

- ✓ Behavior encapsulation
- ✓ Behavior scheduling

Hello World: Data Flow Objects



```
component pss_top {
    buffer msg_buf {
        rand string s;
    }
}

action display_a {
    input msg_buf msg;
    exec body SV = """
        $display("{{msg.s}}");
    """;
}
```

buffer defines *data flow*
stream and **state** also defined

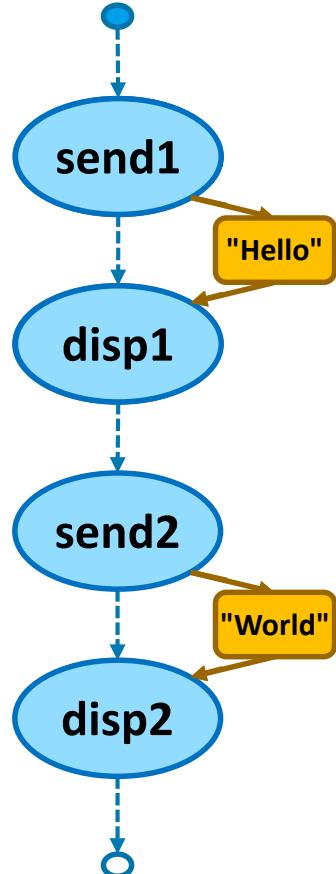
data may be *randomized*

input defines *flow requirement*
output too

"moustache" passes model elements to templates

- ✓ Complex data structures
- ✓ Data flow modeling
- ✓ Constrained random data
- ✓ Reactivity

Hello World: Data Flow Objects



```

component pss_top {
    buffer msg_buf {
        rand string s;
    }
}

action send_a {
    output msg_buf msg;
}

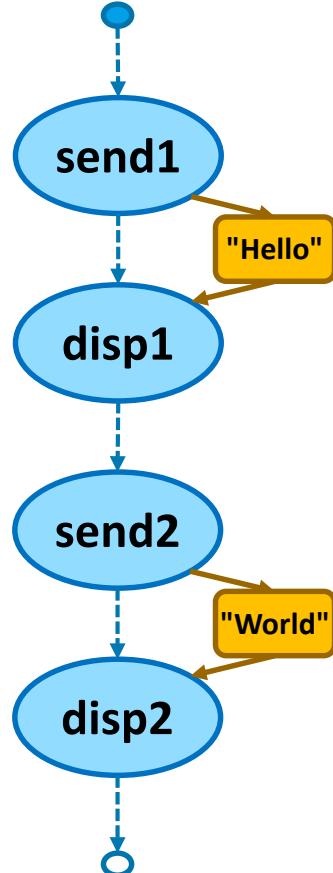
action hello_world_a {
    send_a send1, send2;
    display_a disp1, disp2;
    activity {
        send1 with {msg.s == "Hello ";};
        disp1 with {msg.s == "Hello ";};
        send2 with {msg.s == "World";};
        disp2 with {msg.s == "World";};
        bind send1.msg disp1.msg;
        bind send2.msg disp2.msg;
    }
}

```

The code illustrates a Portable Stimulus component named `pss_top`. It contains a buffer `msg_buf` with a random string `s`. There are two actions: `send_a` (outputting `msg_buf msg`) and `hello_world_a`, which sends `send_a` to `send1` and `send2`, and displays `msg_buf msg` to `disp1` and `disp2`. The `hello_world_a` action also includes an `activity` block with inline constraints for `send1` and `disp1`.

- ✓ Directed testing when desired
- ✓ In-line constraints

Hello World: Packages



```

package hw_pkg;

buffer msg_buf {
    rand string s;
}

component pss_top {
    import hw_pkg::*;

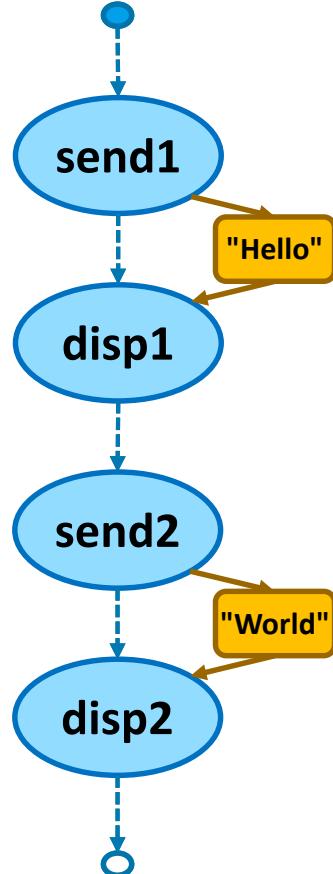
    action display_a {
        input msg_buf msg;
        exec body SV = """
            $display("{{msg.s}}");
        """;
    }
}

on send_a {
    output msg_buf msg;
}

ion hello_world_a {
    end_a send1, send2;
    isplay_a displ1, disp2;
    ctivity {
        send1;
        displ1 with {msg.s == "Hello ";};
        send2;
        disp2 with {msg.s == "World ";};
        bind send1.msg displ1.msg;
        bind send2.msg disp2.msg;
    }
}
  
```

✓ Additional reuse and encapsulation

Hello World: Inferred Actions



```

package hw_pkg {
    buffer msg_buf {
        rand string s;
    }
}

component pss_top {
    import hw_pkg::*;

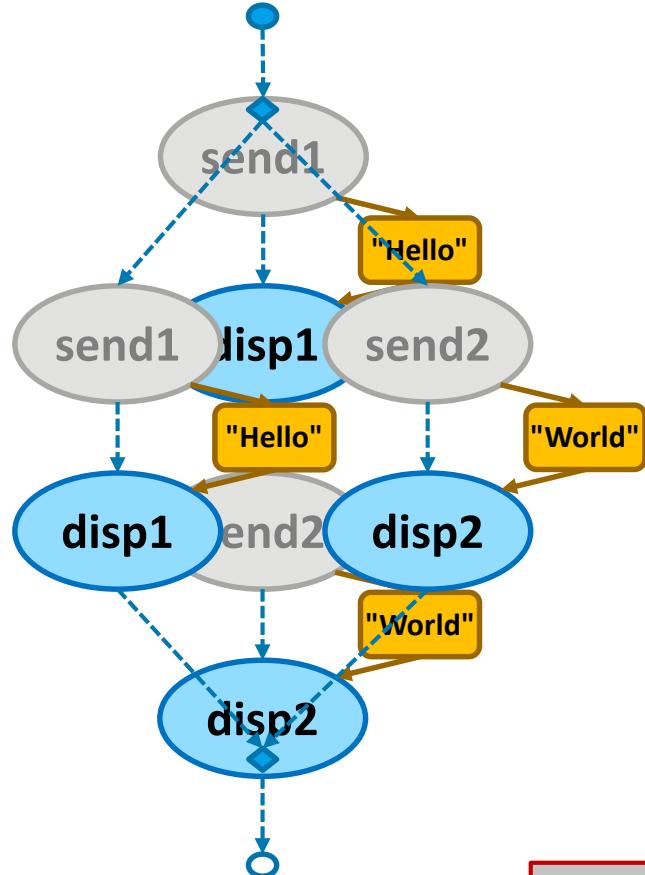
    action display_a {
        input msg_buf msg;
        exec body SV = """
            $display( " {msg.s
            \" \" ");
    }
}

action send_a {
    output msg_buf msg;
}

action hello_world_a {
    send_a send1, send2;
    display_a disp1, disp2;
    activity {
        send1;
        disp1 with {msg.s == "Hello ";};
        send2;
        disp2 with {msg.s == "World ";};
    }
}
    
```

✓ Abstract partial specifications

Hello World: Activity Statements



```

package hw_pkg {
    buffer msg_buf {
        rand string s;
    }
}

component pss_top {
    import hw_pkg::*;

    action display_a {
        input msg_buf msg;
        exec body SV = """
            $display( " {msg.s
            " " ";
    }
}

action send_a {
    output msg_buf msg;
}

action hello_world_a {
    display_a displ1, disp2;
    activity {
        select {
            displ1 with {msg.s == "Hello ";};
            disp2 with {msg.s == "World";};
        }
    }
}
  
```

Randomly choose a branch

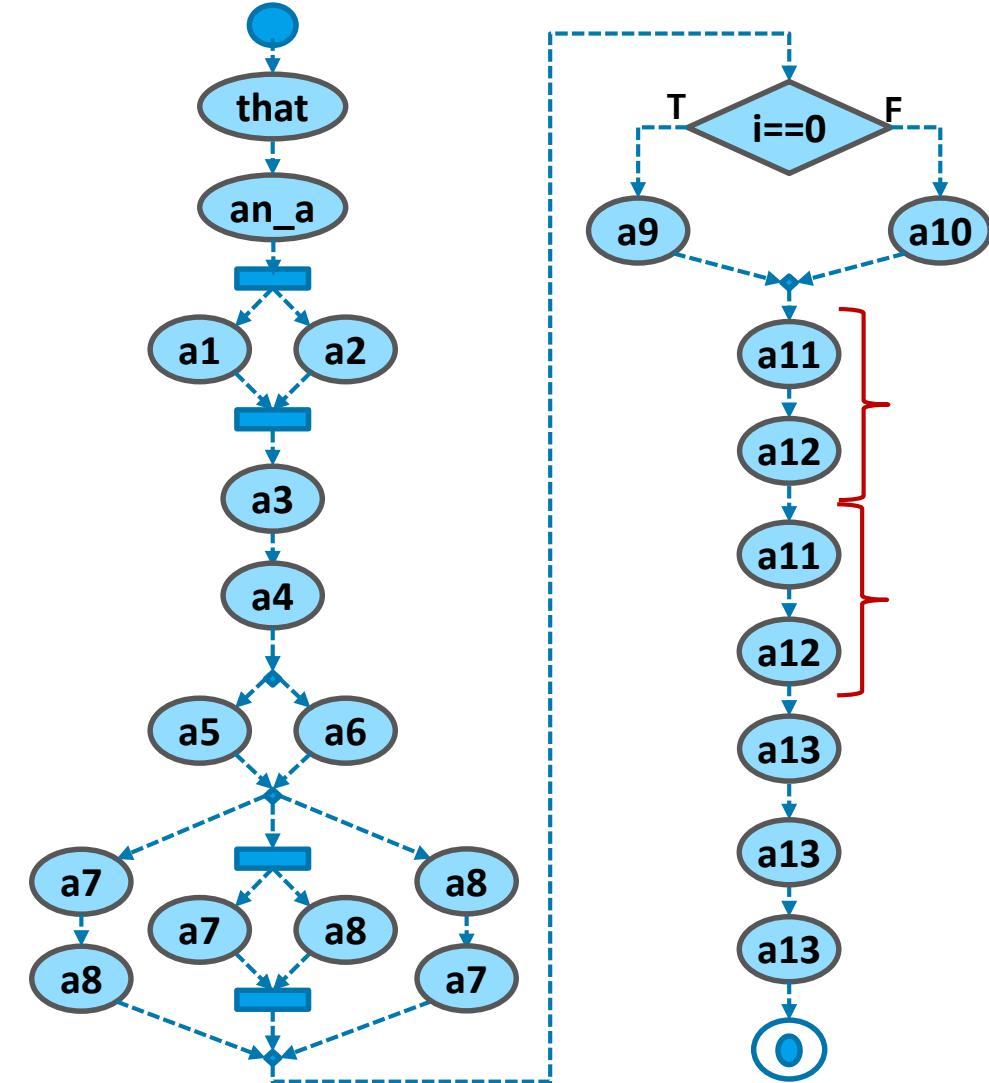
✓ Scenario-level randomization

Activity: Robust Expression of Critical Intent

```

activity {
    that;                                Action instance traversal
    do an_a;                               Anonymous action traversal
    parallel {a1, a2};
    sequence {a3, a4};
    select {a5, a6};
    schedule {a7, a8};                     Subject to
    if (i == 0) {a9;}                      flow/resource
    else {a10;}                            constraints
    repeat (2) {a11, a12};
    foreach (arr[j]) {
        a13 with {a13.val == arr[j];}
    }
}
    
```

✓ Robust scheduling support



Hello World: Extension & Inheritance

hello_a



disp_h

```

extend component pss_top {
    buffer hello_buf : msg_buf {
        constraint {msg.s in["Hello", "Hallo"];}
    }
    action disp_h : display_a {
        override {type msg_buf with hello_buf;}
    }
    action hello_a {
        output hello_buf msg;
    }
}

```

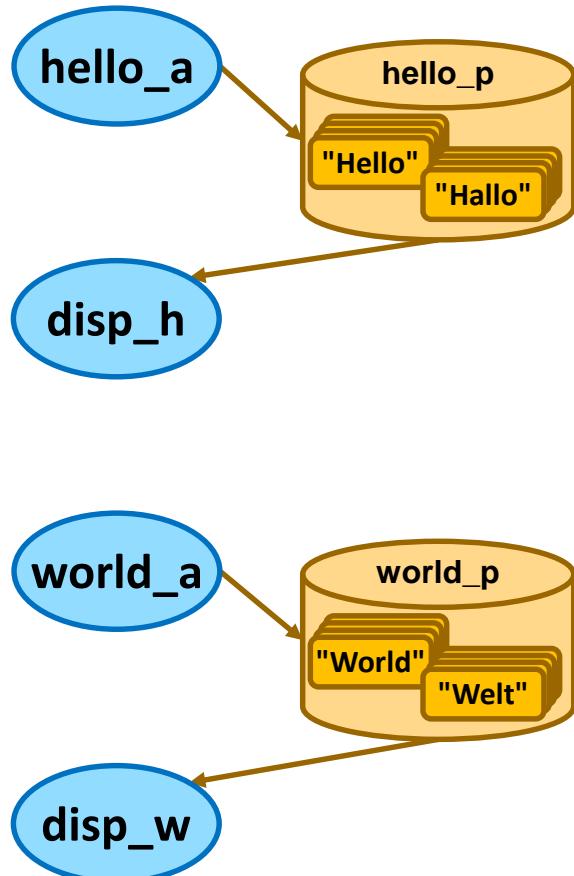
Type extension

Inheritance

Override

- ✓ Type extension
- ✓ Object-oriented inheritance
- ✓ Type (& instance) override

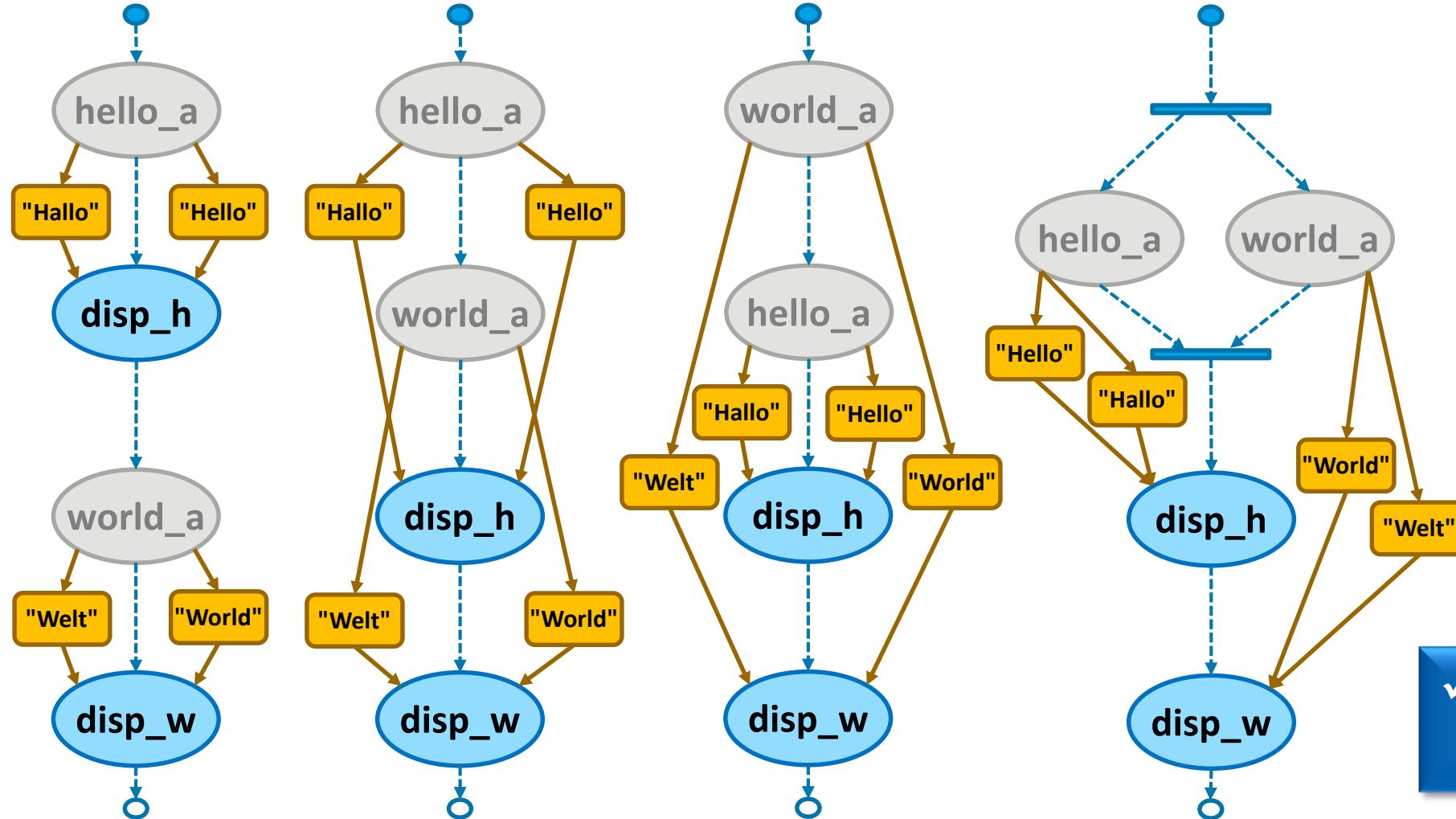
Hello World: Object Pools & Binding



```
extend component pss_top {
    buffer hello_buf : msg_buf {
        constraint {msg.s in["Hello", "Hallo"];}
    }
    action disp_h : display_a {
        override {type msg_buf with hello_buf};
    }
    action hello_a {
        output hello_buf msg;
    }
    pool hello_buf hello_p;
    bind hello_p *;
}
```

- ✓ Constrain data paths
- ✓ Preserve intent

Hello World: Scenarios



```
action hello_world_a {
    activity {
        sequence {
            do disp_h;
            do disp_w;
        }
    }
}
```

anonymous action traversal

✓ Multiple scenarios from simple specification

Hello World: C++

```
package hw_pkg {  
  
    buffer msg_buf {  
  
        rand string s;  
    }  
}
```

```
class hw_pkg : public package {  
    PSSCTOR(hw_pkg, package);  
  
    struct msg_buf : public buffer {  
        PSSCTOR(msg_buf, buffer);  
        rand_attr<std::string> s {"S"};  
    };  
};  
type_decl<hw_pkg> hw_pkg_decl;
```

Hello World: C++

```
component pss_top {
    import hw_pkg::*;

    action display_a {
        input msg_buf msg;
        exec body SV = """
            $display( "{{msg.s}}");
        """;
    }

    action send_a {
        output msg_buf msg;
    }
}
```

```
class pss_top : public component {
    PSSCTOR(pss_top, component);

    class display_a : public action {
        PSSCTOR(display_a, action);
        input <hw_pkg::msg_buf> msg { "msg" };
        exec e {exec::body, "SV",
            "$display(\"{{msg.s}}\")"; };
    };
    type_decl<display_a> display_a_decl;

    class send_a : public action {
        PSSCTOR(send_a, action);
        output <hw_pkg::msg_buf> msg { "msg" };
    };
    type_decl<send_a> send_a_decl;
```

Hello World: C++

```

pool msg_buf msg_p;
bind msg_p *;
action hello_world_a {

    display_a disp1, disp2;

    activity {
        select {
            disp1 with {msg.s == "Hello"};
            disp2 with {msg.s == "World"};
        }
    }
}
    
```

```

pool <hw_pkg::msg_buf> msg_p {"msg_p"};
bind b {msg_p};
class hello_world_a : public action {
    PSSCTOR(hello_world_a, action);
    action_handle<display_a> disp1 {"disp1"},
                                disp2 {"disp2"};
    activity a {
        select {
            disp1.with (disp1->msg->s == "Hello"),
            disp2.with (disp2->msg->s == "World")
        }
    };
    type_decl<hello_world_a> hello_world_a_decl;
};

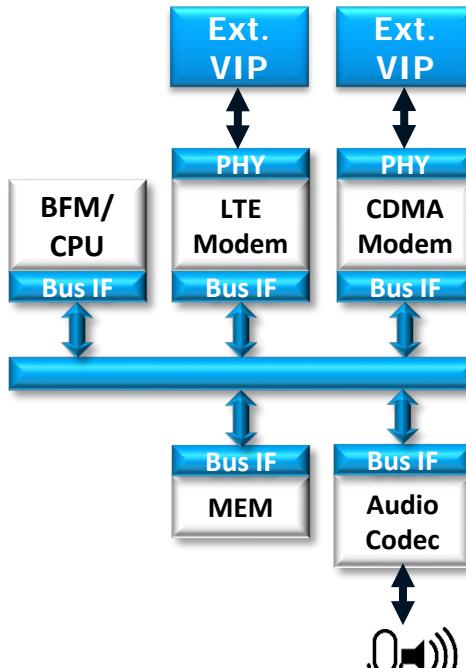
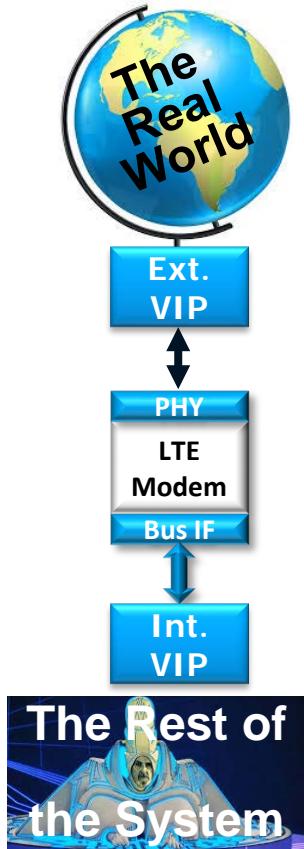
type_decl<pss_top> pss_top_decl;
    
```

A Quick Recap: PSS Gives You...

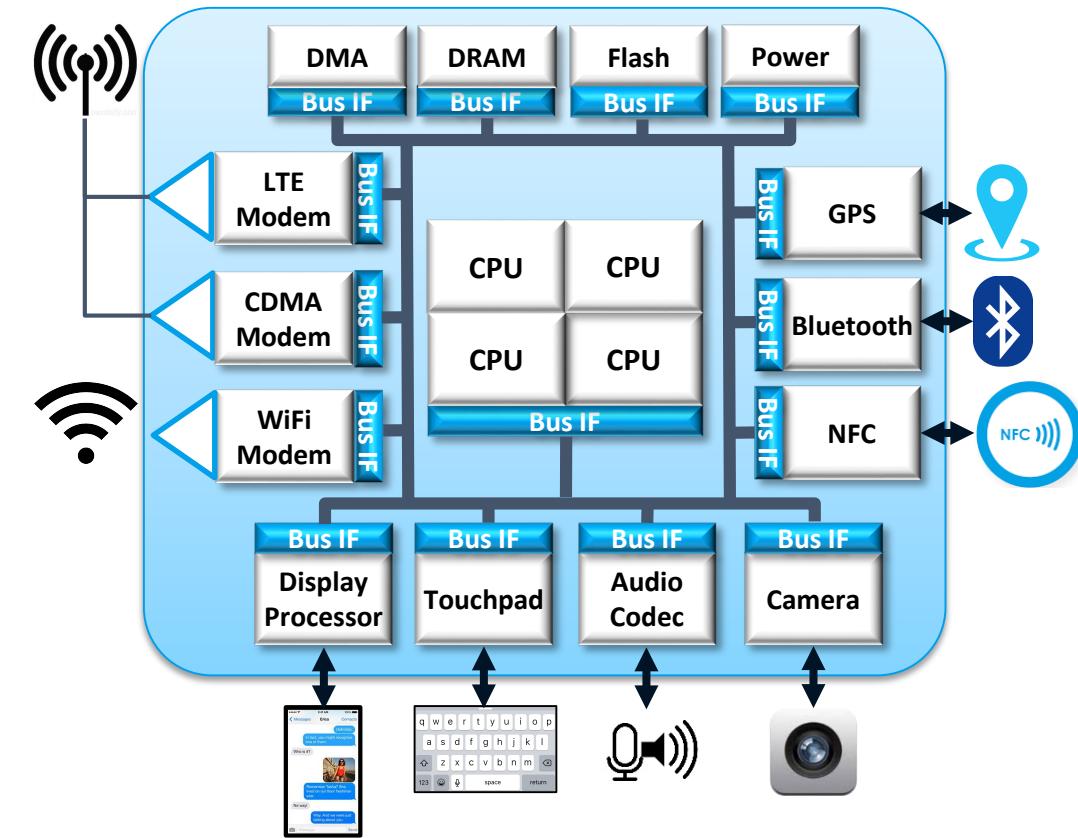
- ✓ Reuse
 - ✓ Composition
 - ✓ Abstract behaviors
 - ✓ Retargetable Implementations
 - ✓ Behavior encapsulation
 - ✓ Behavior scheduling
 - ✓ Complex data structures
 - ✓ Data flow modeling
 - ✓ Constrained randomization
 - ✓ Reactivity
 - ✓ Directed testing when desired
 - ✓ In-line constraints
 - ✓ Additional reuse and encapsulation
 - ✓ Abstract partial specifications
 - ✓ Scenario-level randomization
 - ✓ Robust scheduling support
 - ✓ Type extension
 - ✓ Object instance (e.g., instance) override
 - ✓ Constraint data paths
 - ✓ Preserve intent
 - ✓ Multiple scenarios from simple specification
- But wait! There's more!**

Block-to-System Example

A Block-to-System Example

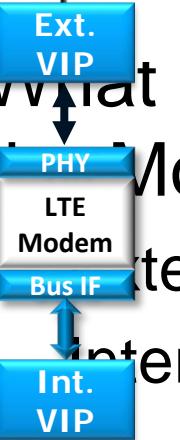


Subsystem



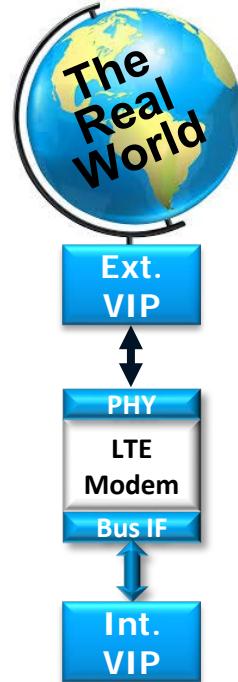
System

Define Actions

-  does the Modem do?
 - receive packet: rx
 - transmit packet: tx
 - What data flow objects does the Modem use?
 - External Interface: packet
 - Internal Interface: datStr
- 



- What does the External IP do?
 - send packets
 - receive packets
- What does the Internal IP do?
 - Store datStrs
 - Retrieve datStrs

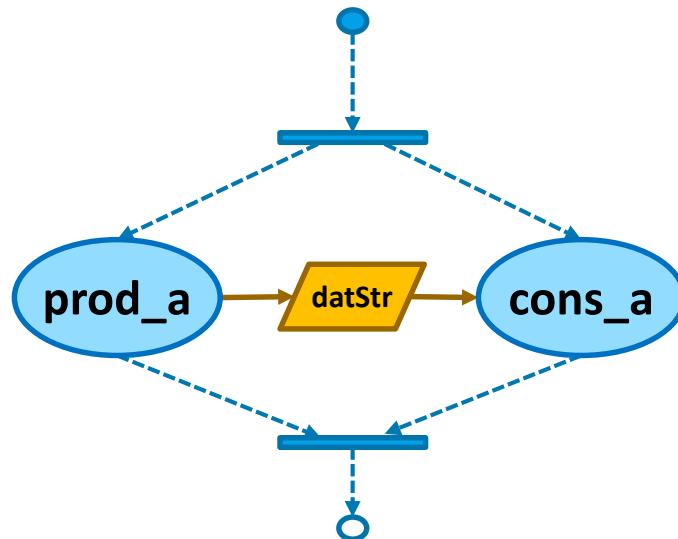


Define Data Flow Objects

enum defines a set of *integral named constants*

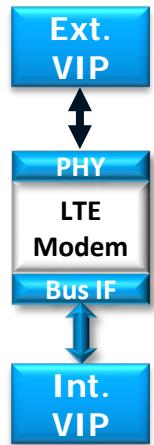
stream requires *parallel* producer-consumer execution

rand fields are randomized



```

package data_flow_pkg{
    enum dir_e {inb=0, outb};
    stream datStr {
        rand dir_e dir;
        rand bit [7:0] length;
        rand bit [31:0] addr;
    }
    stream packet {
        rand dir_e dir;
        rand bit [15:0] size;
        bit [47:0] MAC_src;
        bit [47:0] MAC_dst;
    }
}
    
```



The LTE Modem Component

function imports a
procedural interface

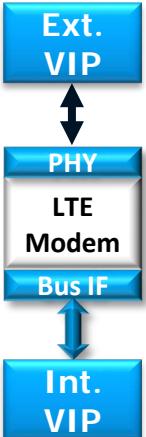
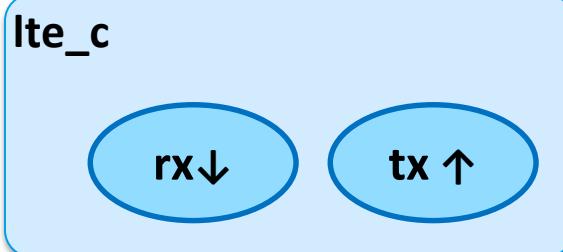
```
package modem_funcs {
    import data_flow_pkg::dir_e;
    function void set_mode(dir_e dir);
}

component lte_c {
    import data_flow_pkg::*;
    import modem_funcs::*;

    action tx_a {
        input datStr bPkt;
        output packet pkt;
        constraint {pkt.dir == outb; bPkt.dir == outb;}
    }

    exec body {
        set_mode(pkt.dir);
    }
}
...
```

procedural interface
 passes elements
 to/from **exec** blocks



The VIP Components

extvip_c

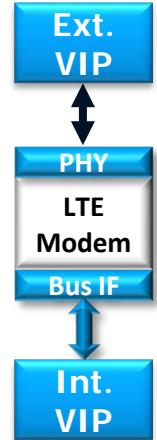


```
component extvip_c {
    import data_flow_pkg::packet;
    action send_a {
        output packet pkt;
        constraint {pkt.dir == inb;}
    }
    action receive_a {
        input packet pkt;
        constraint {pkt.dir == outb;}
    }
}
```

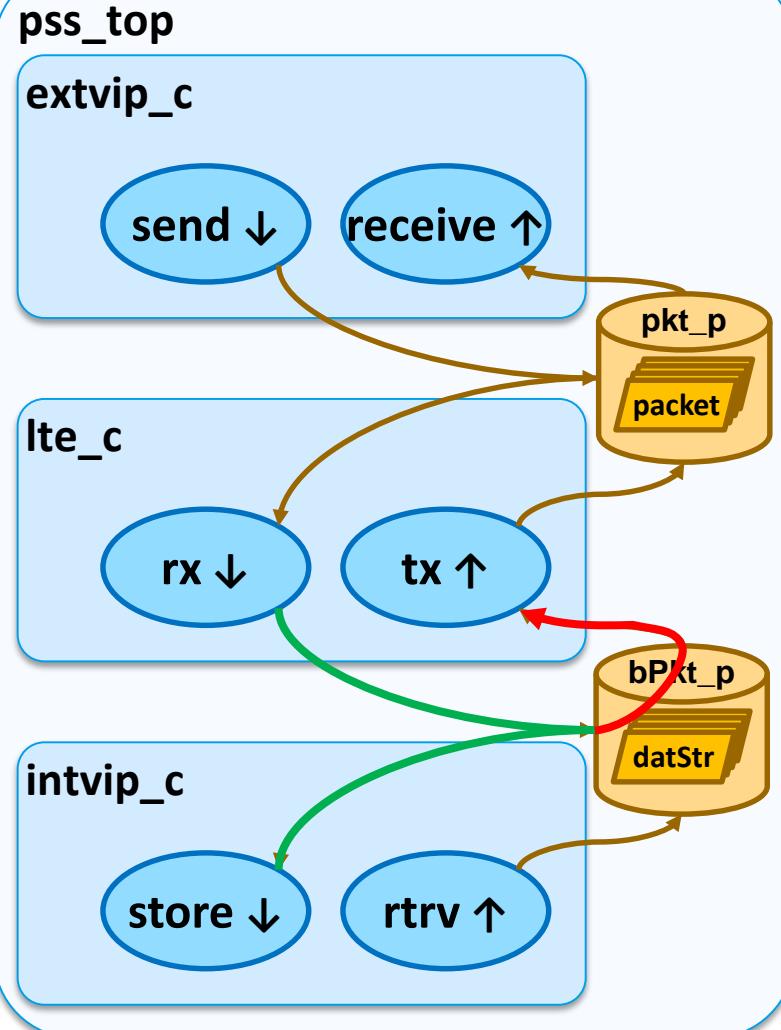
intvip_c



```
component intvip_c {
    import data_flow_pkg::datStr;
    action store_a {
        input datStr pkt;
        constraint {pkt.dir == inb;}
    }
    action rtrv_a {
        output datStr pkt;
        constraint {pkt.dir == outb;}
    }
}
```



Putting it Together

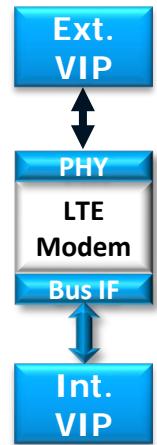


```
component pss_top {
    import data_flow_pkg::*;

    extvip_c xvip;
    lte_c lte;
    intvip_c ivip;

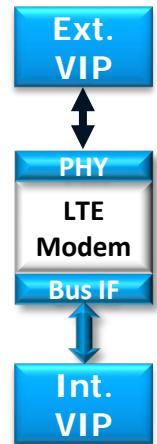
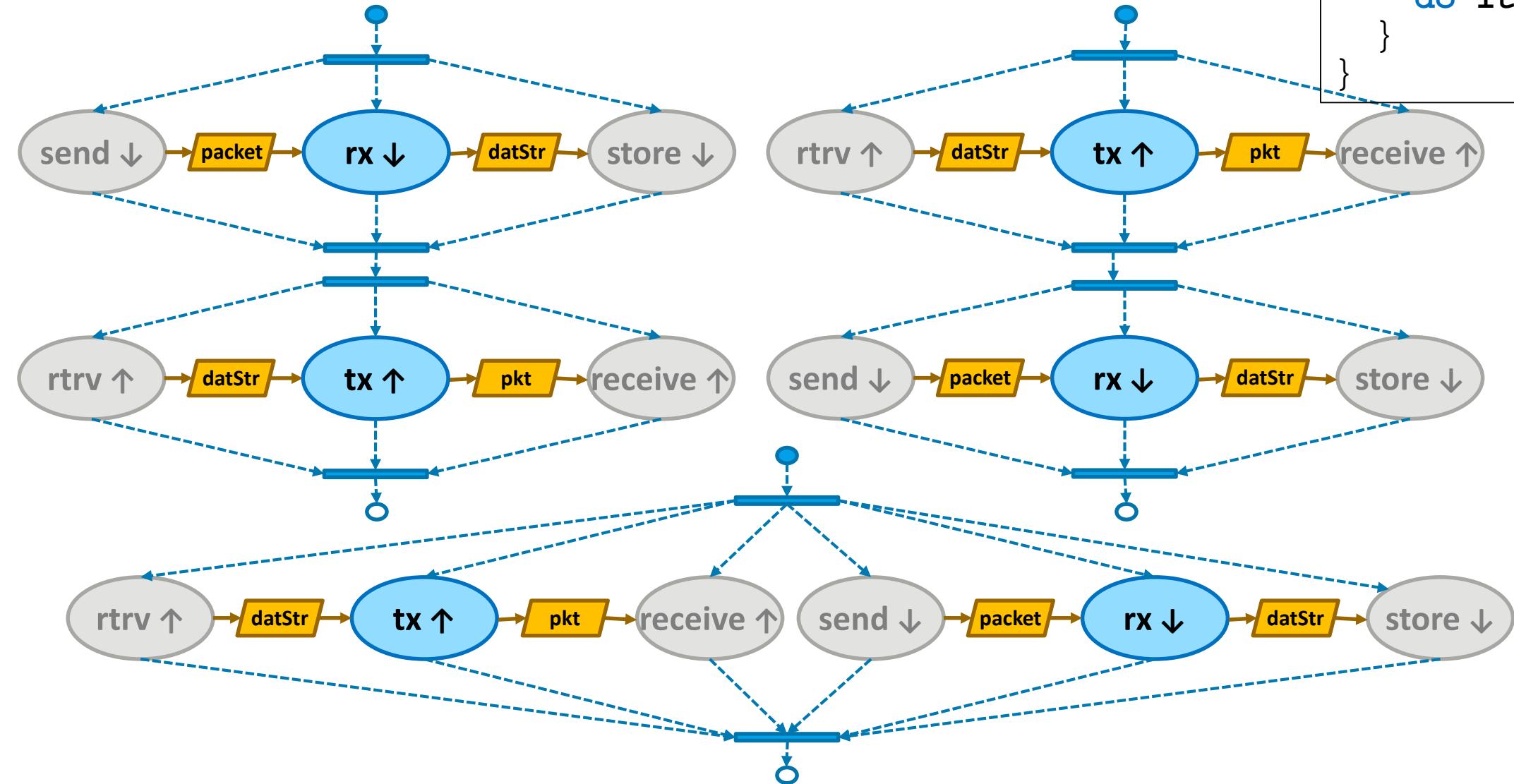
    pool packet pkt_p;
    bind pkt_p {xvip.*, lte.*};
    pool datStr bPkt_p;
    bind bPkt_p {ivip.*, lte.*};

    action test {
        activity {
            schedule {
                do lte_c::rx_a;
                do lte_c::tx_a;
            }
        }
    }
}
```



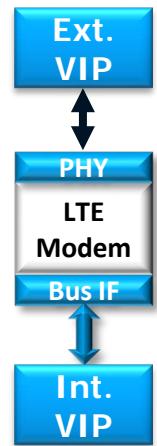
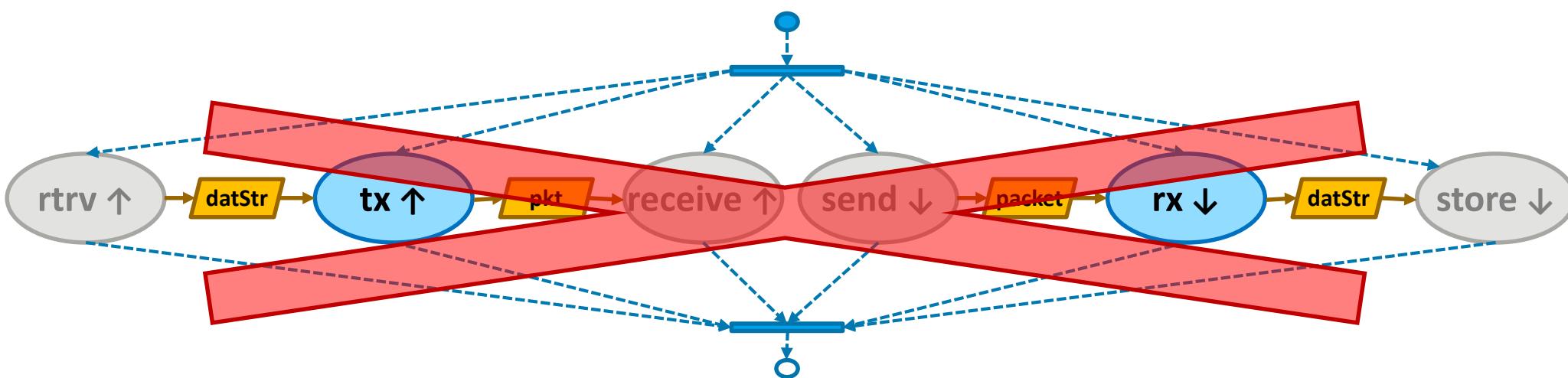
Putting it Together

```
activity {
    schedule {
        do lte_c::rx_a;
        do lte_c::tx_a;
    }
}
```



Resources: Target-Specific Constraints

- What if the Modem is half-duplex?
 - Prevent rx & tx from running in parallel
- PSS models target-specific *resources*
 - May be assigned to an action for its duration
 - Exclusive (*locked*) or non-exclusive (*shared*)

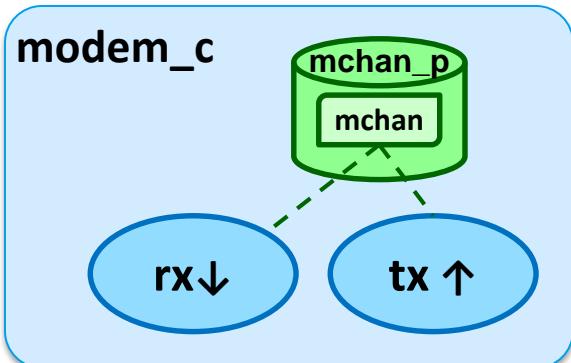


The Modem Component + Resources

resource defines a resource object

pool defaults to size == 1

lock declares exclusive access

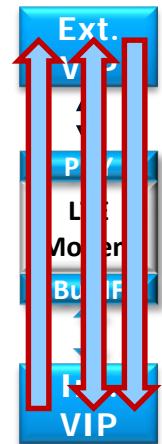


```
component lte_c {
    import data_flow_pkg::*;
    import modem_funcs::*;

    resource mchan_r {.../* struct */};

    pool[1] mchan_r mchan_p;
    bind mchan_p *;

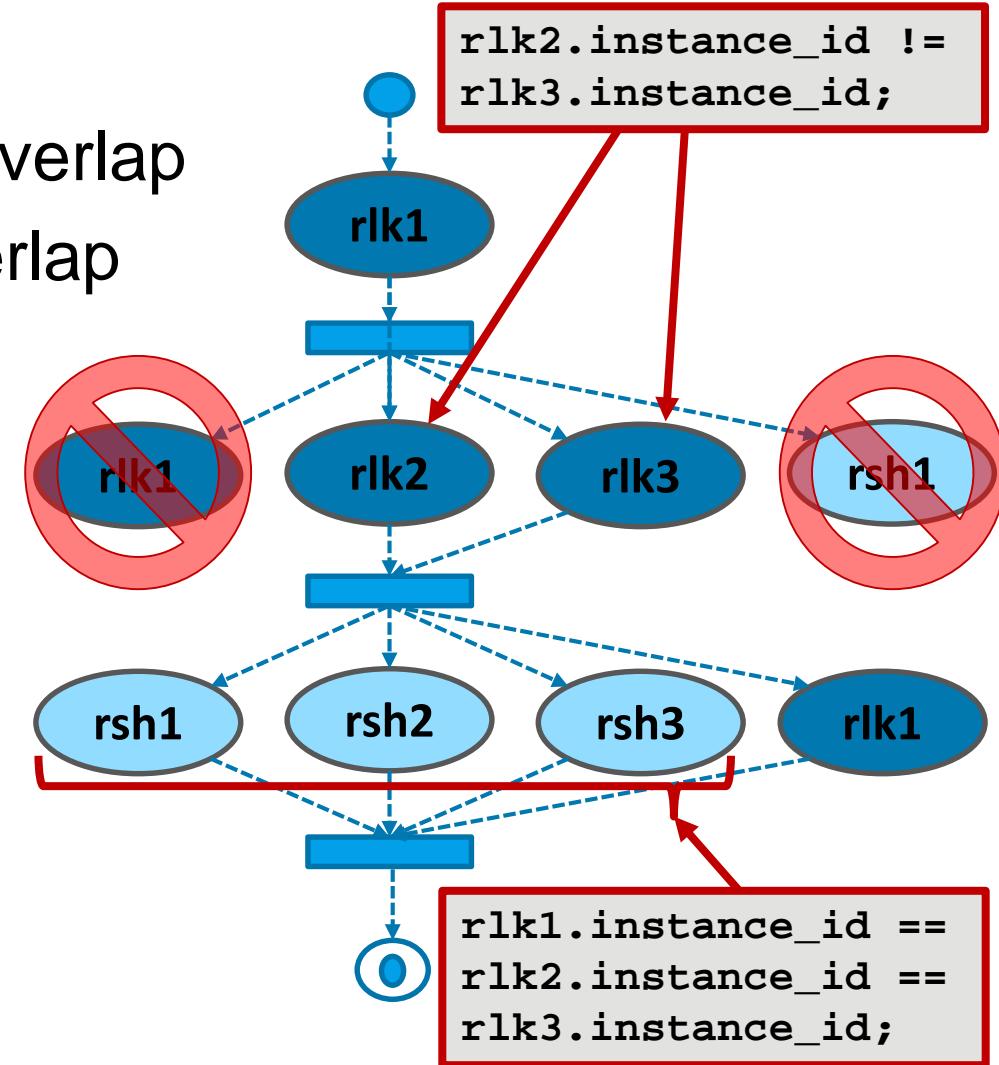
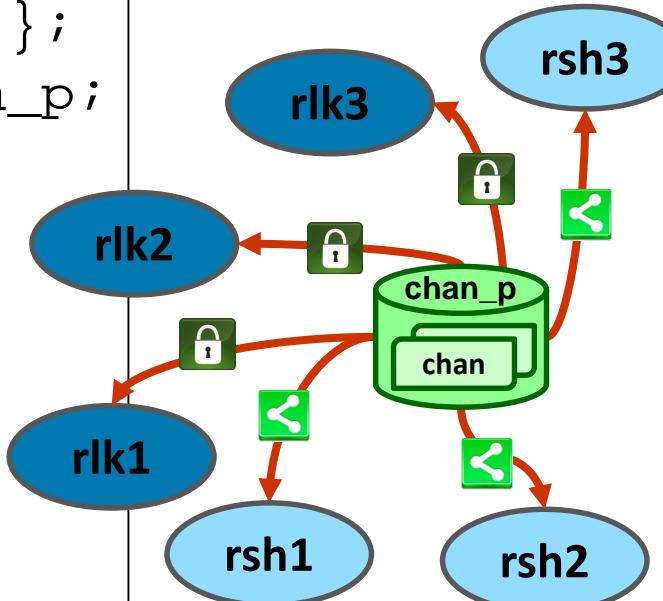
    action rx_a {
        input packet pkt;
        output datStr bPkt;
        lock mchan_r mchan;
        constraint {pkt.dir == inb; bPkt.dir == inb;}
    }
    ...
}
```



Claiming Resource Objects

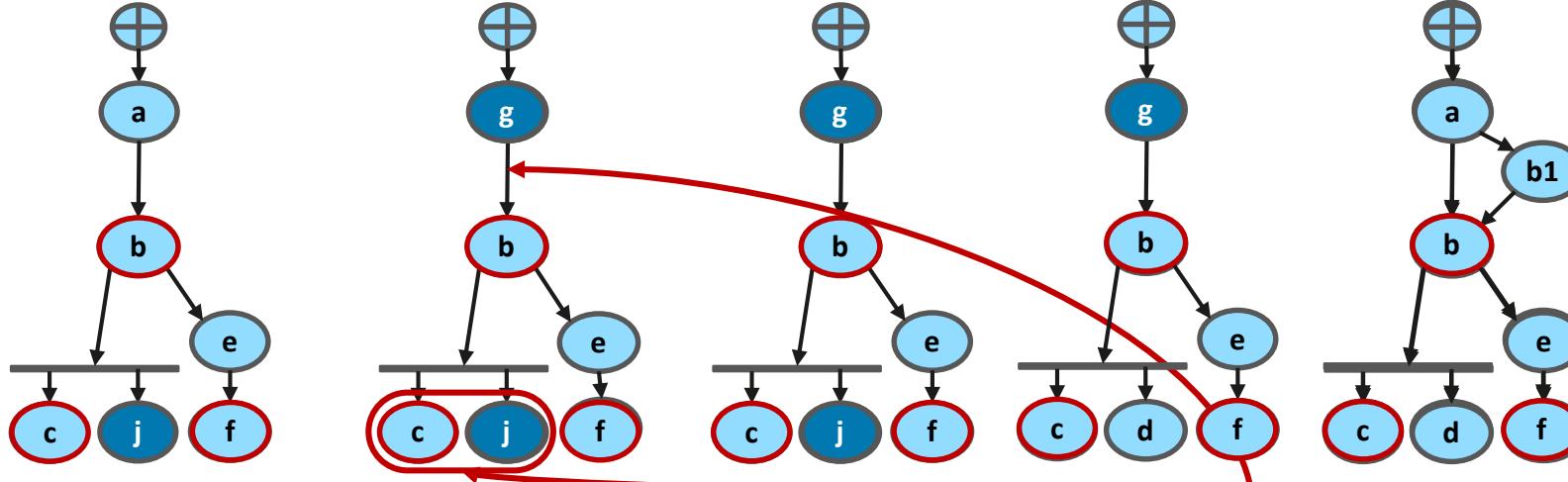
- Actions may *lock* or *share* resources
 - Actions that *lock* a given resource may not overlap
 - Actions that *share* a given resource may overlap

```
resource chan_r {...};
pool [2] chan_r chan_p;
bind chan_p {*};
action rlk_a {
    lock chan_r chan;
    ...
};
action rsh_a {
    share chan_r chan;
    ...
};
```



- A total of *size* locking actions may execute in parallel for a given resource pool

Solution Space Mapping



Partial
Specifications
are *Flexible*

```
action test_top {
    do_a a; do_b b;
    do_c c; do_d d;
    do_e e; do_f f;

    activity {
        a;
        b;
        select {
            parallel { c; d; }
            {e; f;}
        }
    }
}
```

```
action test_top {
    do_b b;
    do_c c;
    do_f f;

    activity {
        b;
        select {
            f;
        }
    }
}
```

```
buffer mbuf {...};

action do_a {
    output mbuf m;
    ...
};

action do_b {
    input mbuf m;
    output mbuf o;
    ...
};

action do_g {
    output mbuf m;
    ...
};
```

```
stream mstr {...};

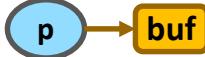
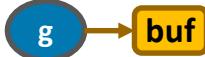
action do_c {
    input mstr s;
    ...
};

action do_d {
    output mstr s;
    ...
};

action do_j {
    output mstr m;
    ...
};
```

Resolving a Partial Specification

```
action test_top {
    activity {
        b;
        select {
            c;
            f;
        }
    }
}
```

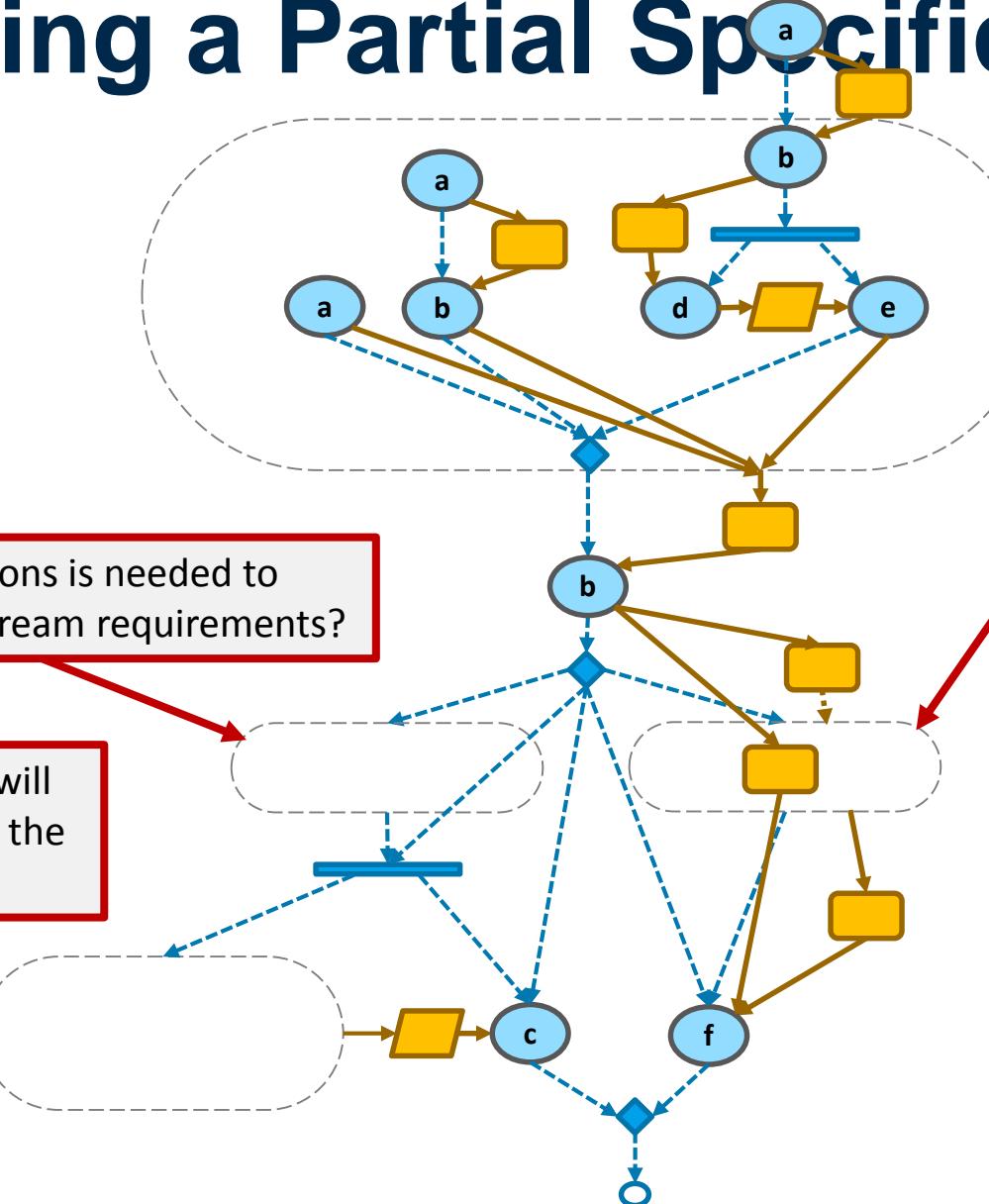


What set of actions is needed to support downstream requirements?

What set of actions will produce a **stream** of the correct type?

What combination of known actions will produce a **buf** of the correct type?

Are there any **resource** conflicts that constrain the possible scheduling?



End of Part 1

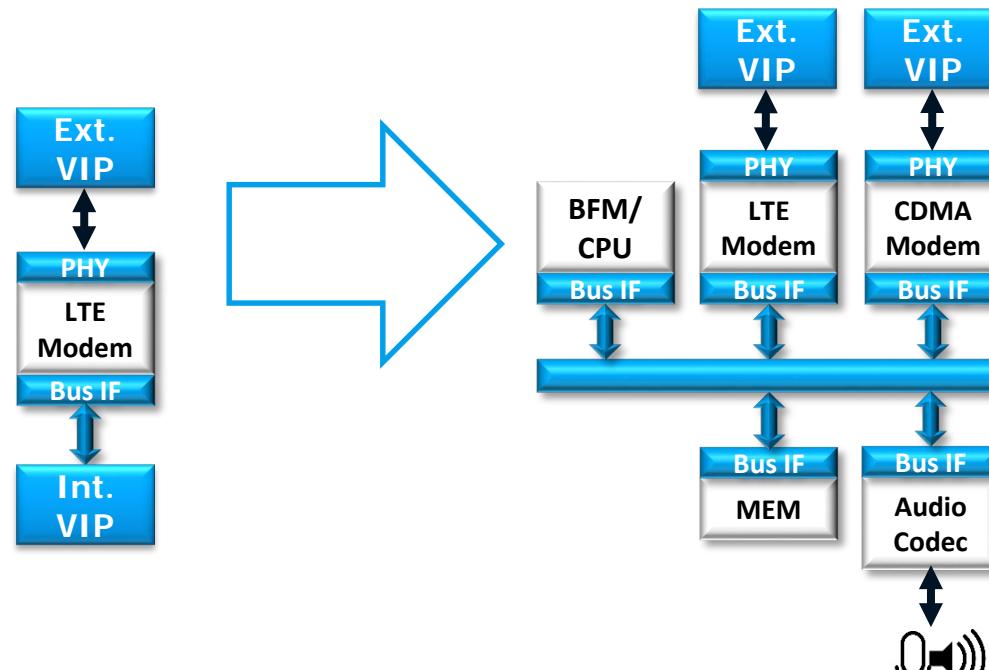
Portable Test and Stimulus: The Next Level of Verification Productivity is Here

Part 2

Accellera Portable Stimulus Working Group

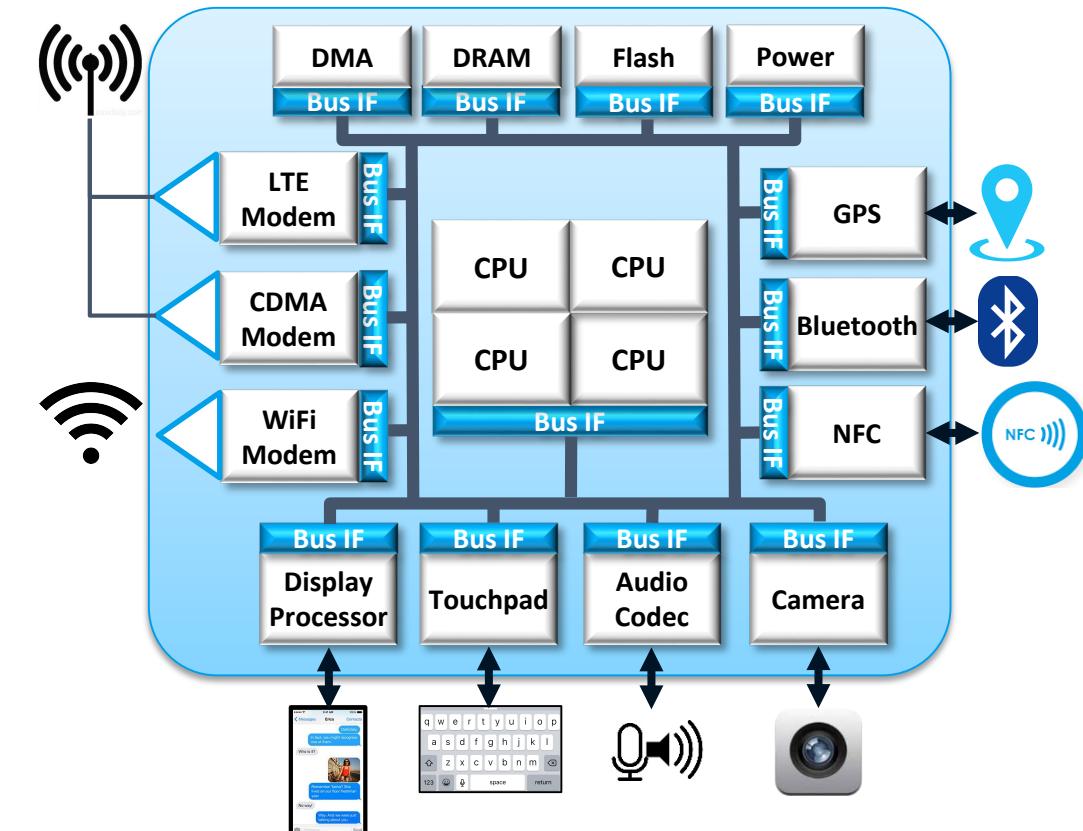
2/26/2018

A Block-to-System Example



Block

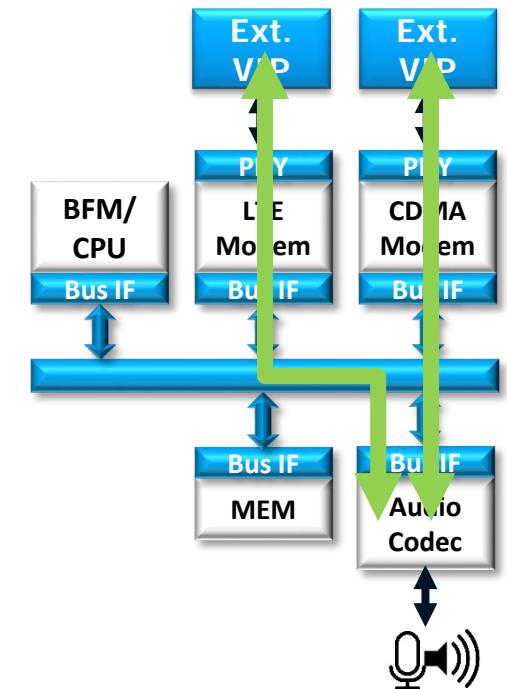
Subsystem



System

Modem Sub-system

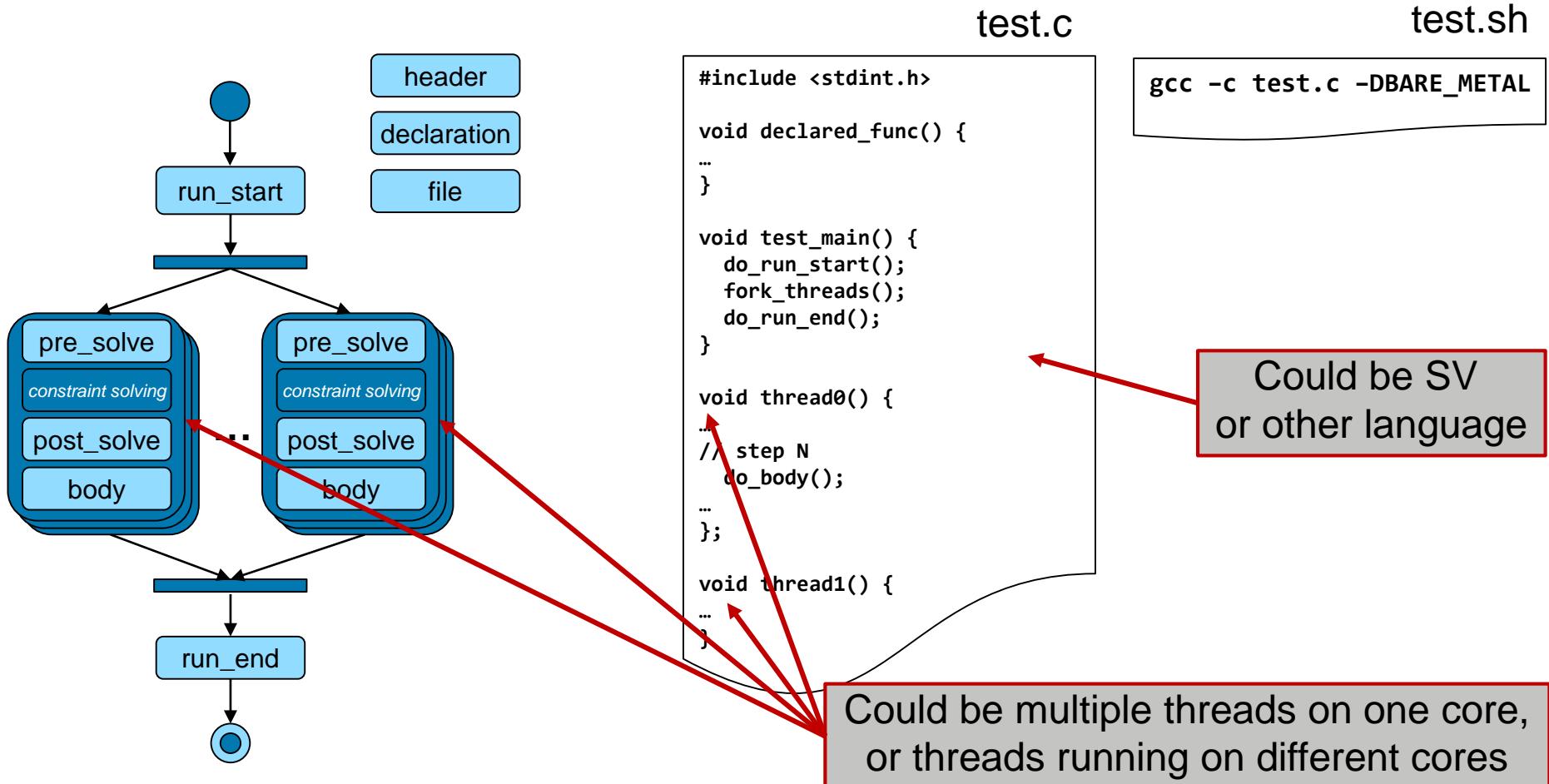
- Manage Voice Calls
- Can use either
 - LTE Modem, OR
 - CDMA Modem
- Both modems exchange common datStr data with Audio Codec
- *Stream* relationship between Modem and Audio Codec:
 - both must operate concurrently



Subsystem

Exec Block Types

Specify mapping of PSS entities to their implementation



The CDMA Modem Component

more function imports

```
package modem_funcs {
    function bit [47:0] CDMA_MAC_src();
    function bit [47:0] CDMA_MAC_dst();
    function bit [31:0] CDMA_data_buf();
}
```

```
component cdma_c {
    import data_flow_pkg::*;
    import modem_funcs::*;
}
```

```
stream datStr {
    rand dir_e dir;
    rand bit [7:0] length;
    rand bit [31:0] addr;
```

```
action rx_a {
    input packet pkt;
    output datStr bPkt;
    constraint {pkt.dir == inb; bPkt.dir == inb;}
```

post-solve exec block
runs after randomization

cdma_c

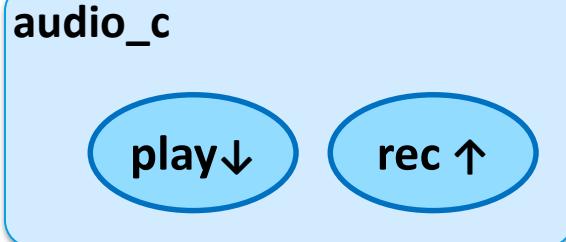


```
exec post_solve {
    bPkt.addr = CDMA_data_buf();
```

...

Bus IF
↑
Int. VIP

The Audio Codec Component



```

package audio_funcs {
    function void play(bit[31:0] addr, bit[7:0] len);
    function void record(bit[31:0] addr);
}

component audio_c {
    import audio_funcs::*;

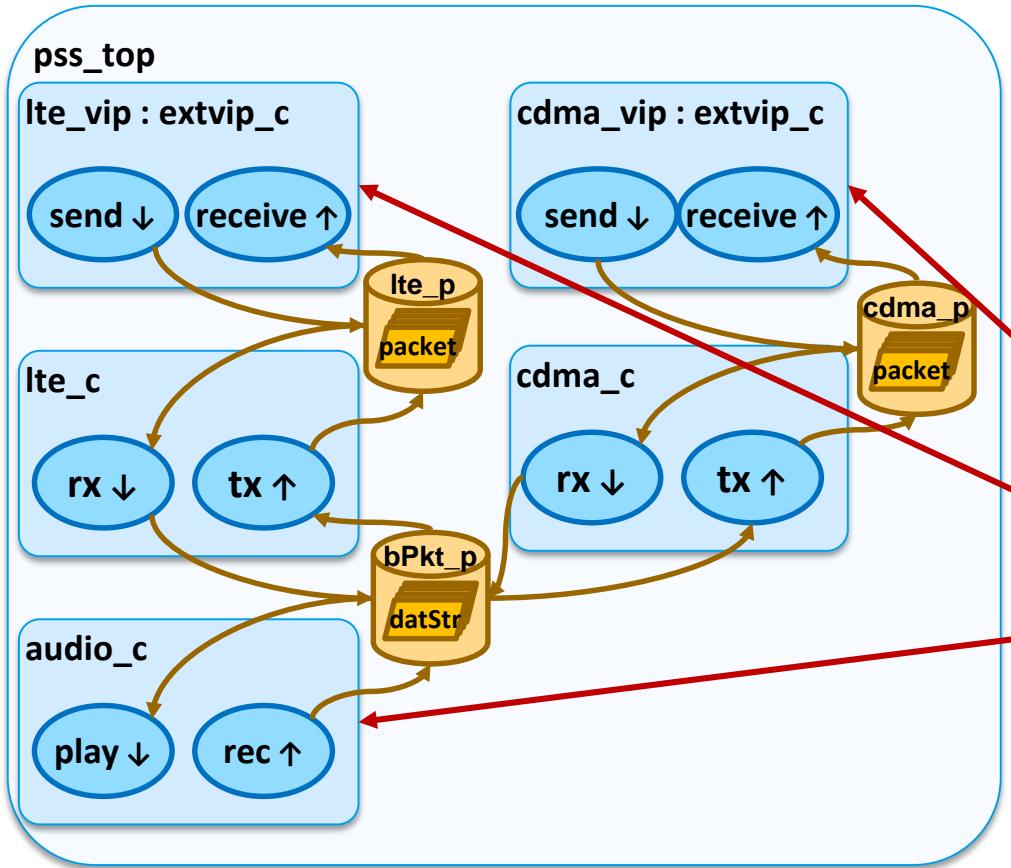
    action rec_a {
        output datStr bPkt;
        constraint {bPkt.dir == outb;
                     bPkt.length == 1024; }

        exec body {
            record(bPkt.addr);
        }
    }
}

```



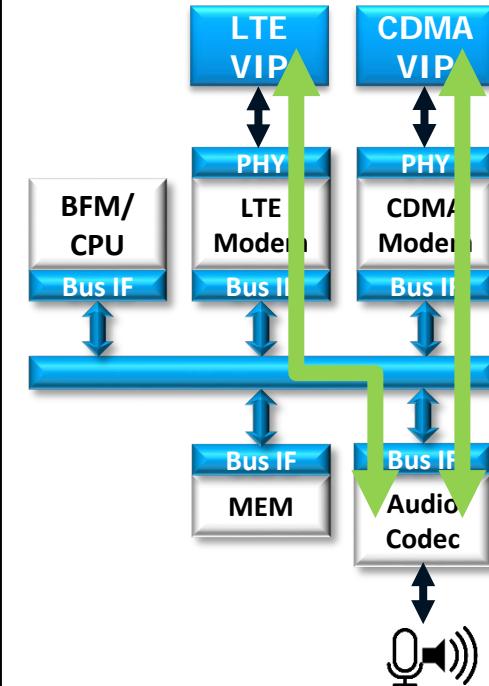
Putting it Together



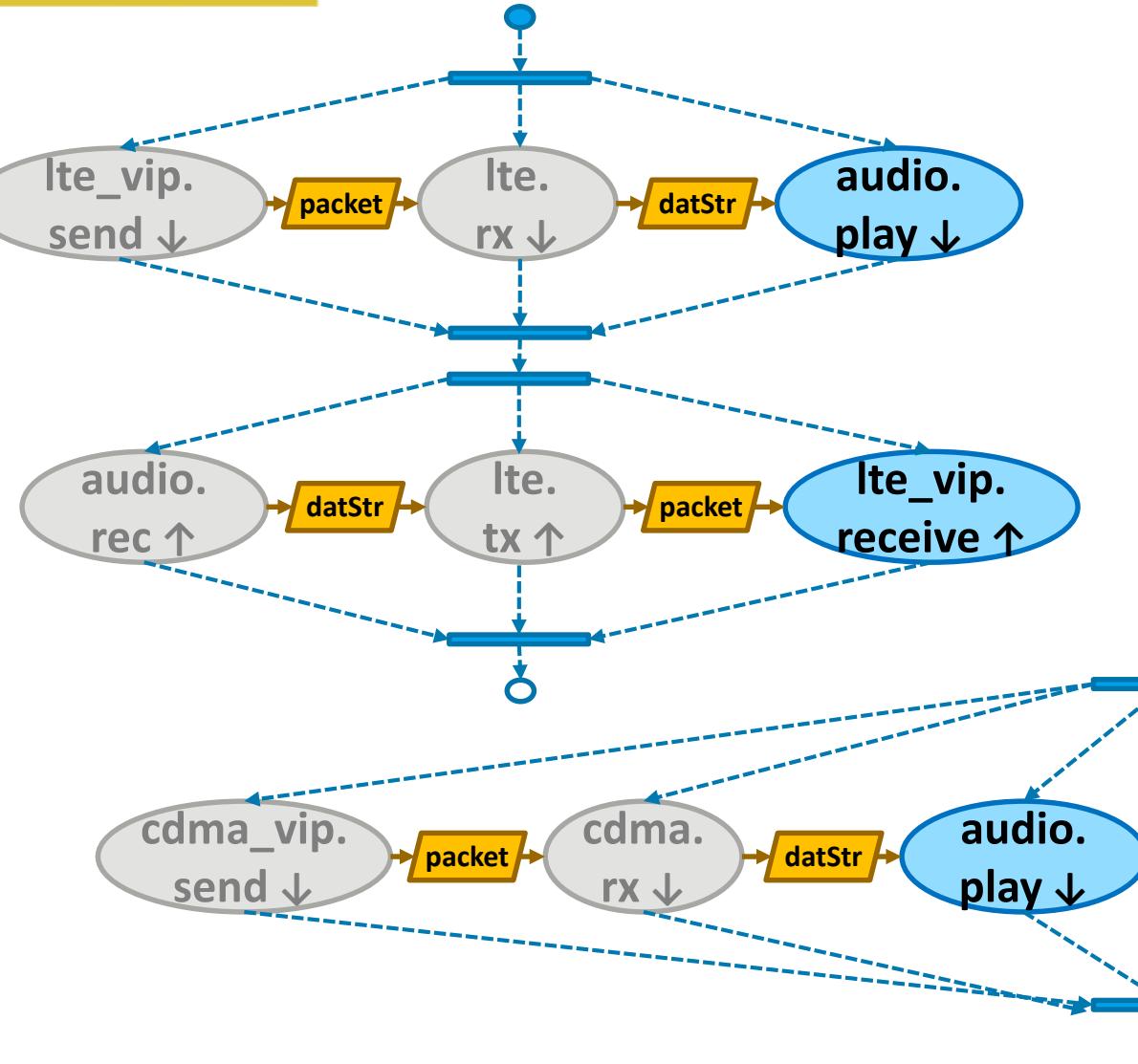
```
component pss_top {
    import data_flow_pkg::*;

    extvip_c lte_vip, cdma_vip;
    lte_c lte;
    cdma_c cdma;
    audio_c audio;

    action test {
        activity {
            schedule {
                do audio_c::play_a;
                do extvip_c::receive_a;
            }
        }
    }
}
```

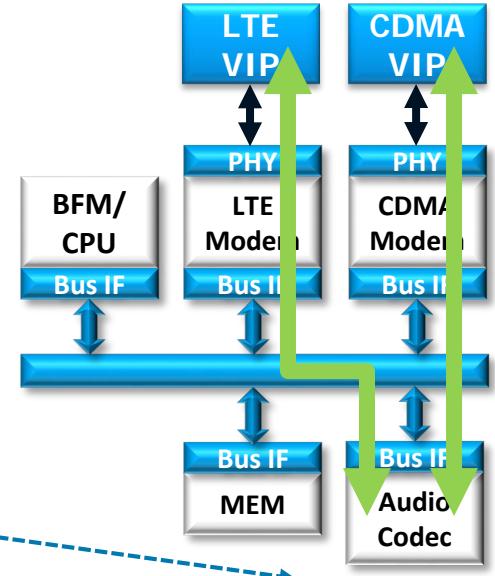


Subsystem Scenarios



```

activity {
    schedule {
        do audio_c::play_a;
        do extvip_c::receive_a;
    }
}
  
```



Layering in Power Scenarios

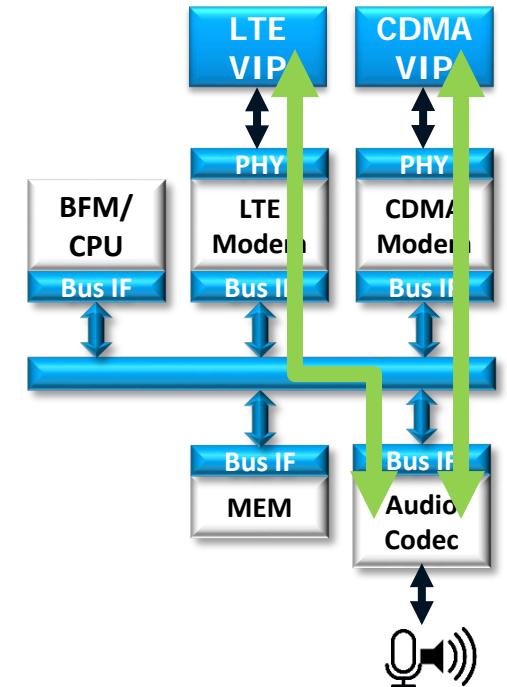
state flow object preserves persistent state
initial used to set start value of persistent state

```
package power_state {
    function void radio_on();
    function void radio_off();

    enum radio_state_e { on, off };

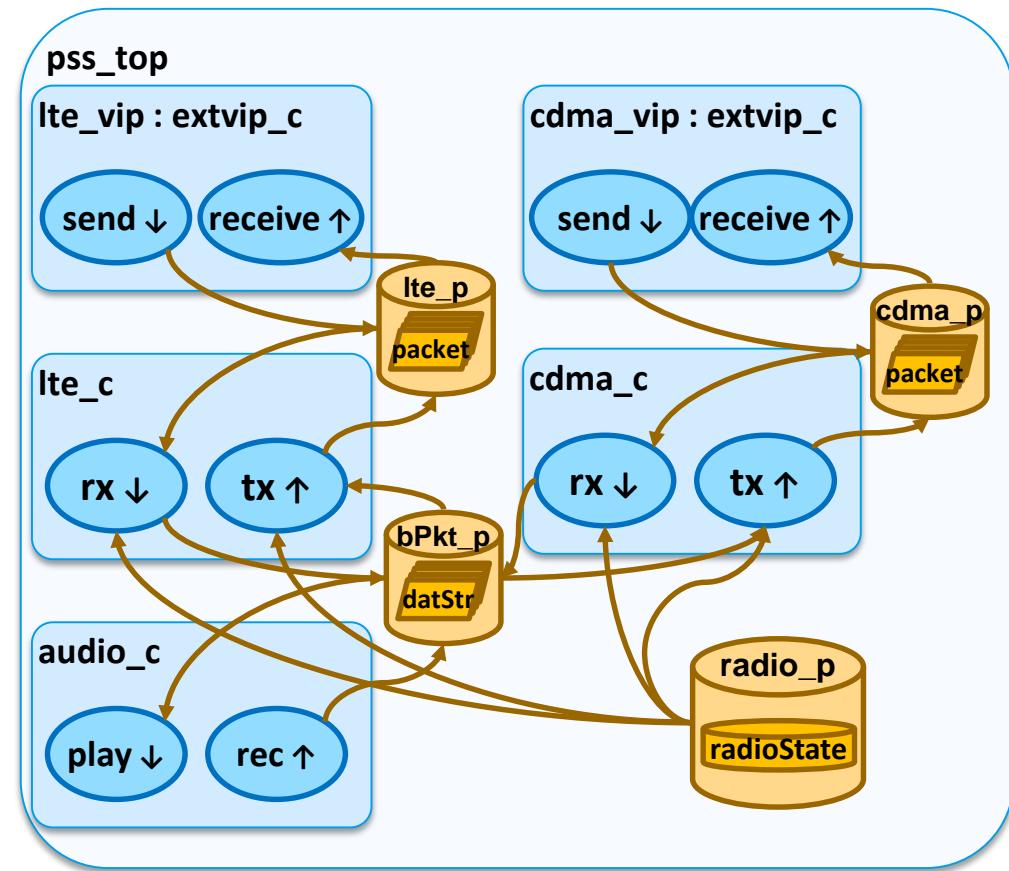
    state radioState {
        rand radio_state_e rstate;
        constraint
    }
    ...
}

extend component pss_top {
    ...
    pool radioState radio_p;
    bind radio_p *;
}
```



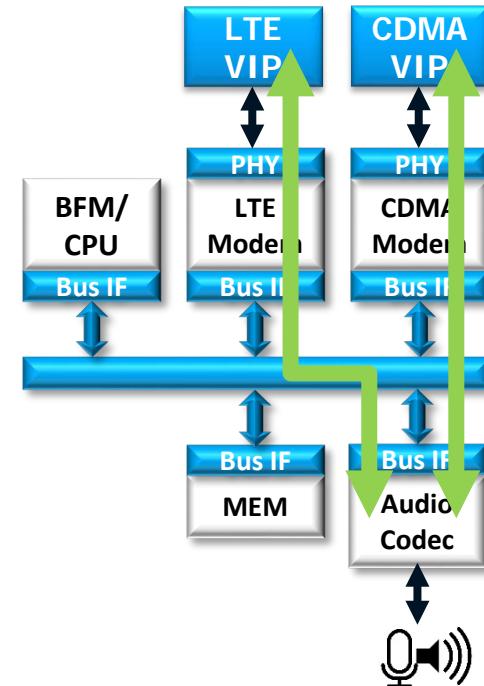
Subsystem

Layering in Power Scenarios



```
package power_state {
    extend action lte_c::tx_a {
        input radioState in_s;
        constraint
            in_s.rstate == on;
    }

    extend action cdma_c::tx_a {
        input radioState in_s;
        constraint
            in_s.rstate == on;
    }
    ...
}
```



Subsystem

Layering in Power Scenarios

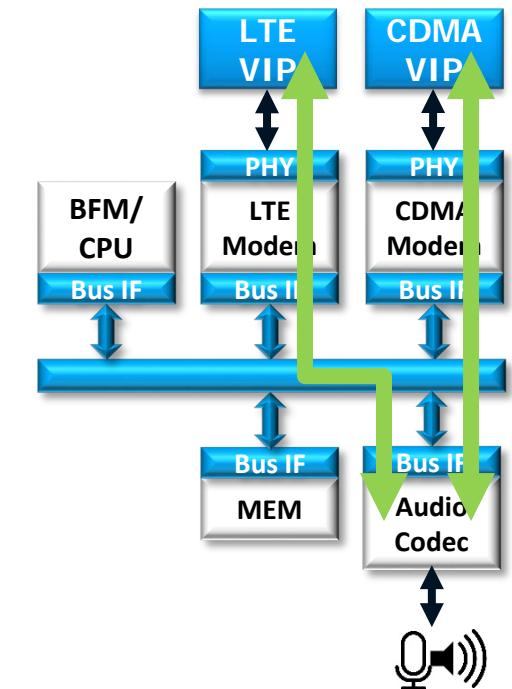
outputs a **radioState** flow object

may only run if previous **rstate** was **off**

set next **rstate** to **on**

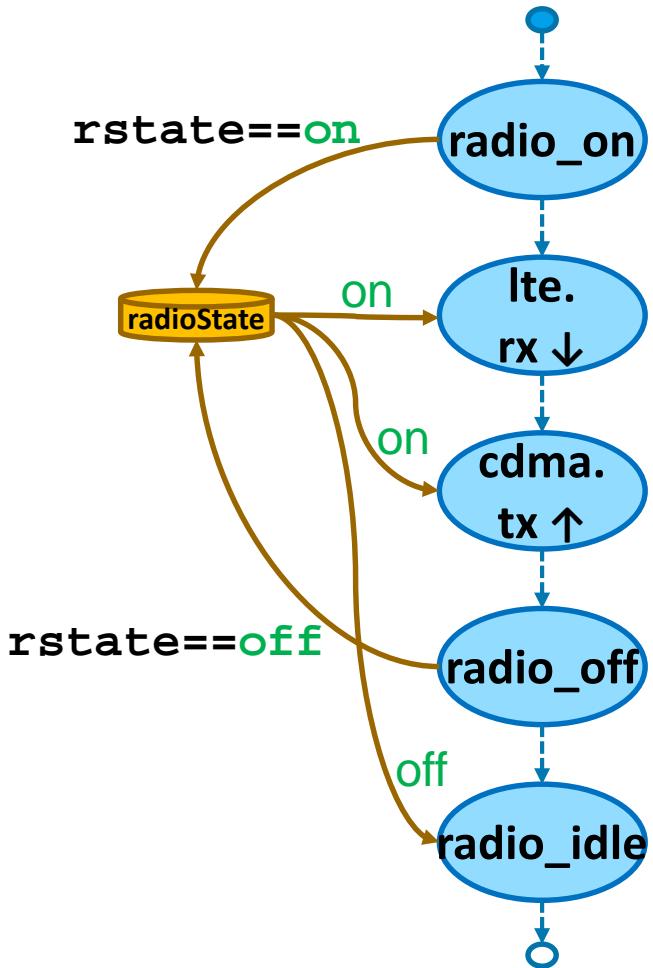
turn on the radio

```
extend component pss_top {
    action radio_off_a {
        output radioState out_s;
        constraint
            out_s.prev.rstate == on;
        constraint
            out_s.rstate == off;
        exec body {
            radio_off();
        }
    }
}
```



Subsystem

Layering in Power Scenarios

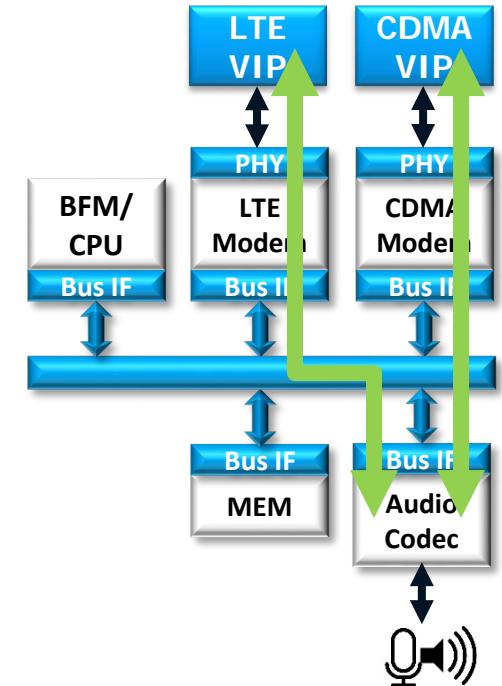


```

extend component pss_top {

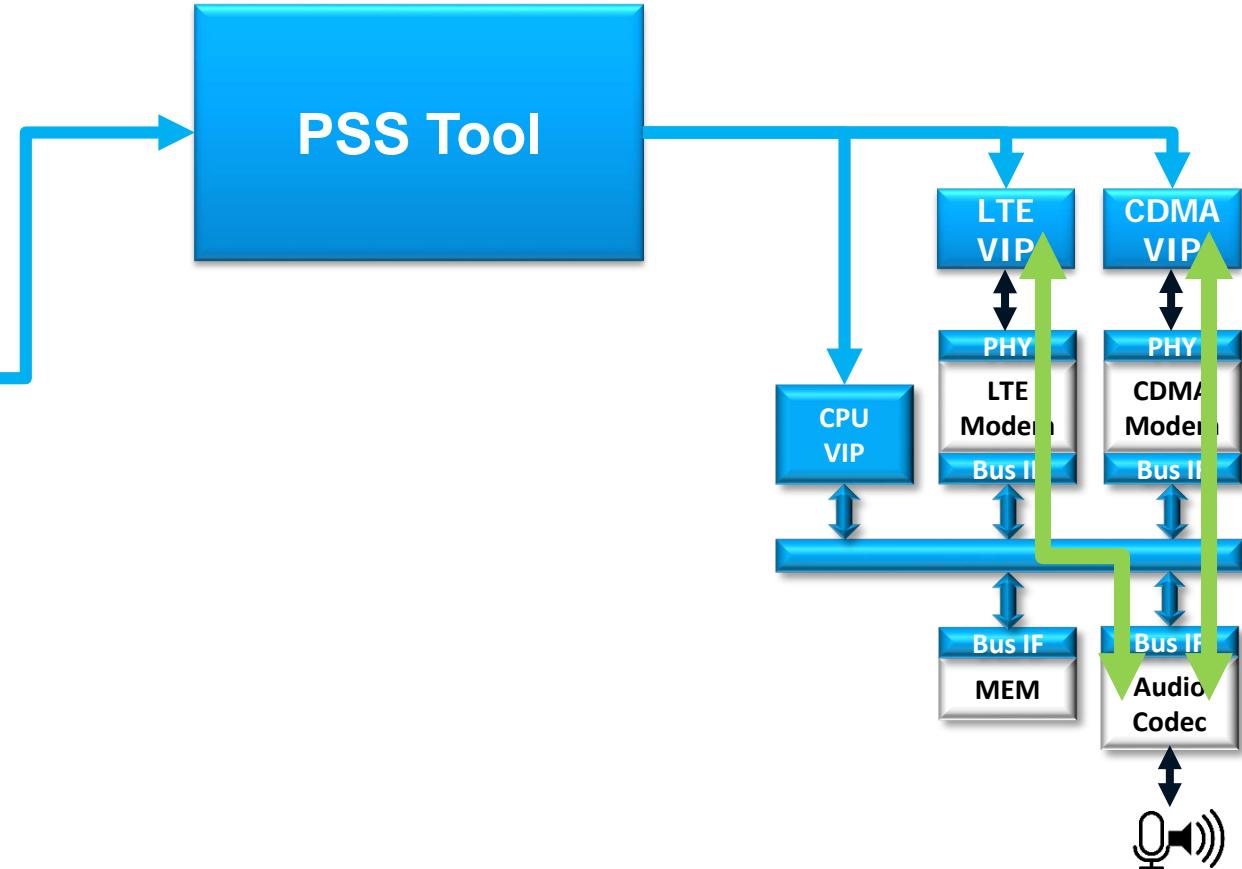
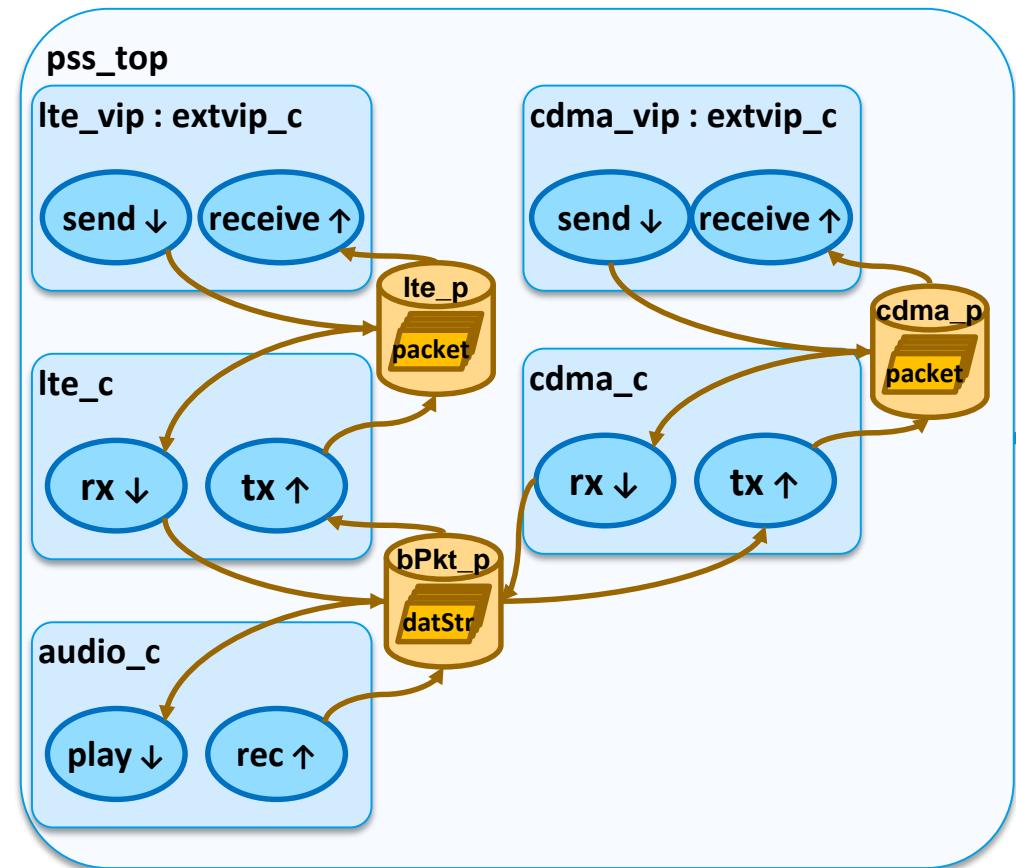
    action radio_idle_a {
        input radioState in_s;
        constraint in_s.rstate == off;
    }

    action test {
        activity {
            select {
                do radio_idle_a;
                schedule {
                    do audio_c::play_a;
                    do extvip_c::receive;
                }
            }
        }
    }
}
  
```



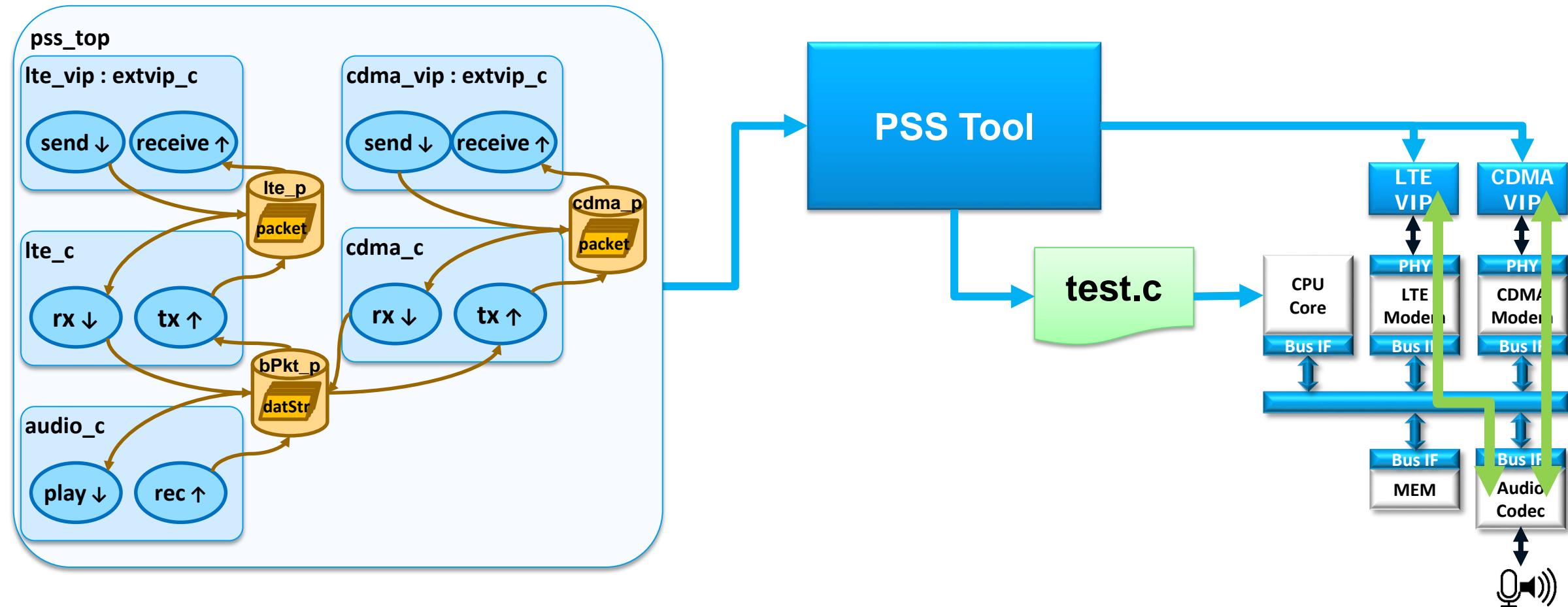
Subsystem

UVM Tool Flow



Subsystem

UVM + C-Test Tool Flow



Portable Stimulus Coverage

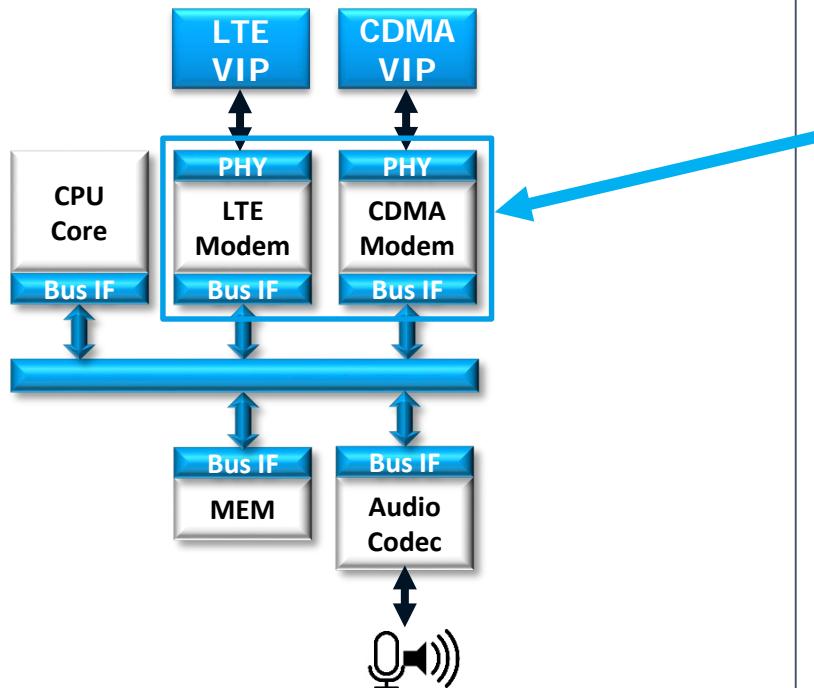
- Coverage constructs derived from SV
 - Support cross, illegal, ignore and others
 - Keyword is change from covergroup -> coverspec
- Coverage is currently data-centric
 - Monitor values and ranges on action/struct fields
- More coverage types may be added
 - Action Coverage
 - Scenario (Action Sequence) Coverage
 - Datapath Coverage
 - Resource Coverage

Formalization of system
level scenarios and models



Ability to formally describe
coverage of the legal
scenarios and attributes

Coverage



```

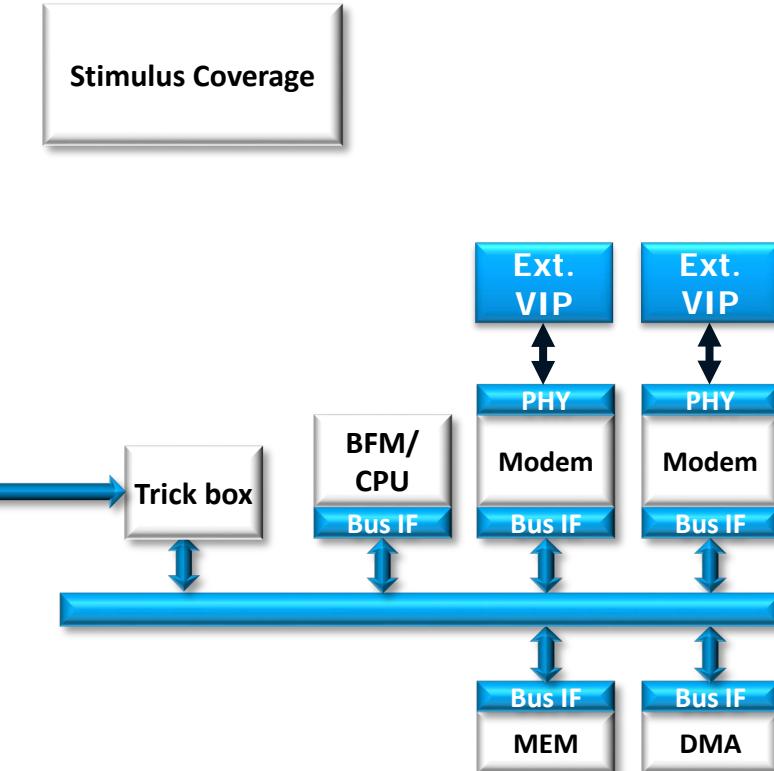
action setup_modem {
    enum direction_e {TRANSMIT, RECEIVE, BOTH};
    rand direction_e direction;
    unsigned int baud_rate;
    unsigned int packet_size;
    unsigned bit [1:0] destination_addr;

    exec body {... }

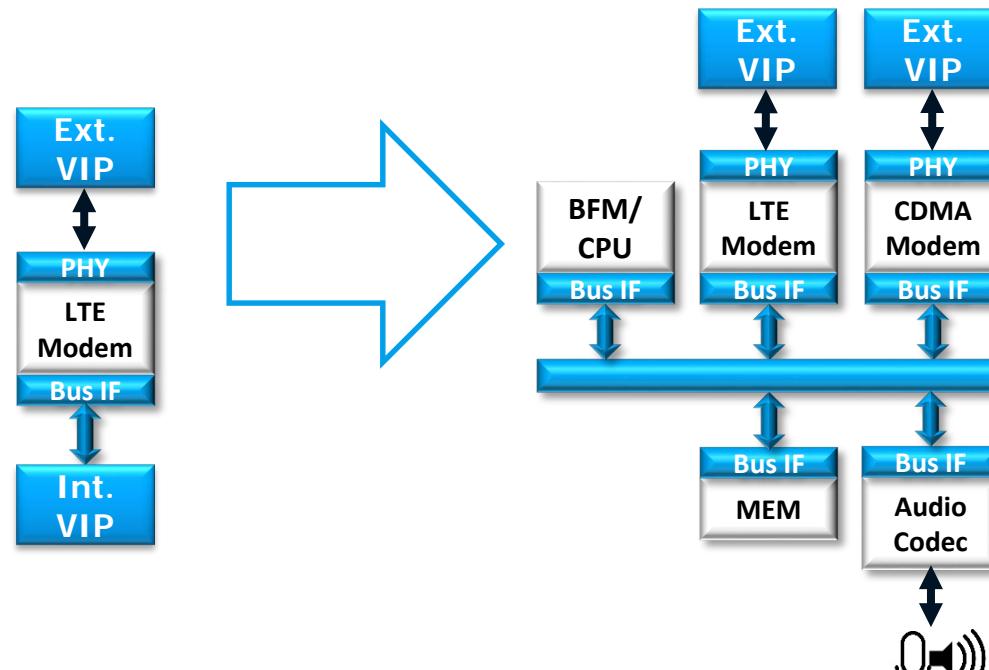
coverspec modem_initialization (init_modem) {
    constraint baud_len_c {
        if (direction == TRANSMIT) {
            baud_rate in [28000,3192704, 4196704];
        }
    }
    baud: coverpoint init_modem.packet_size {
        bins size [28000 ... 4296704]/32;
    }
    dir : coverpoint transmit_dir_tx {
        bins transmit = {TRANSMIT};
        bins receive = {RECEIVE};
        bins bidi = {BOTH};
    }
    transmit_type_invld : cross transmit_dir_tx, addr {
        ignore addr ? (direction == TRANSMIT) : 1;
    }
    address: coverpoint addr ;
}
  
```

Monitoring Coverage

- Stimulus monitoring
 - Generation time tool can output what it generated/scheduled
 - As long as test “passes”, the coverage data is valid
- Runtime state monitoring
 - Requires generation of monitoring code
 - May be C/C++ code running on target cpu
 - e.g. data sent out “trickbox” mechanism
 - May be “off-chip” monitoring via test ports or other communication ports



A Block-to-System Example



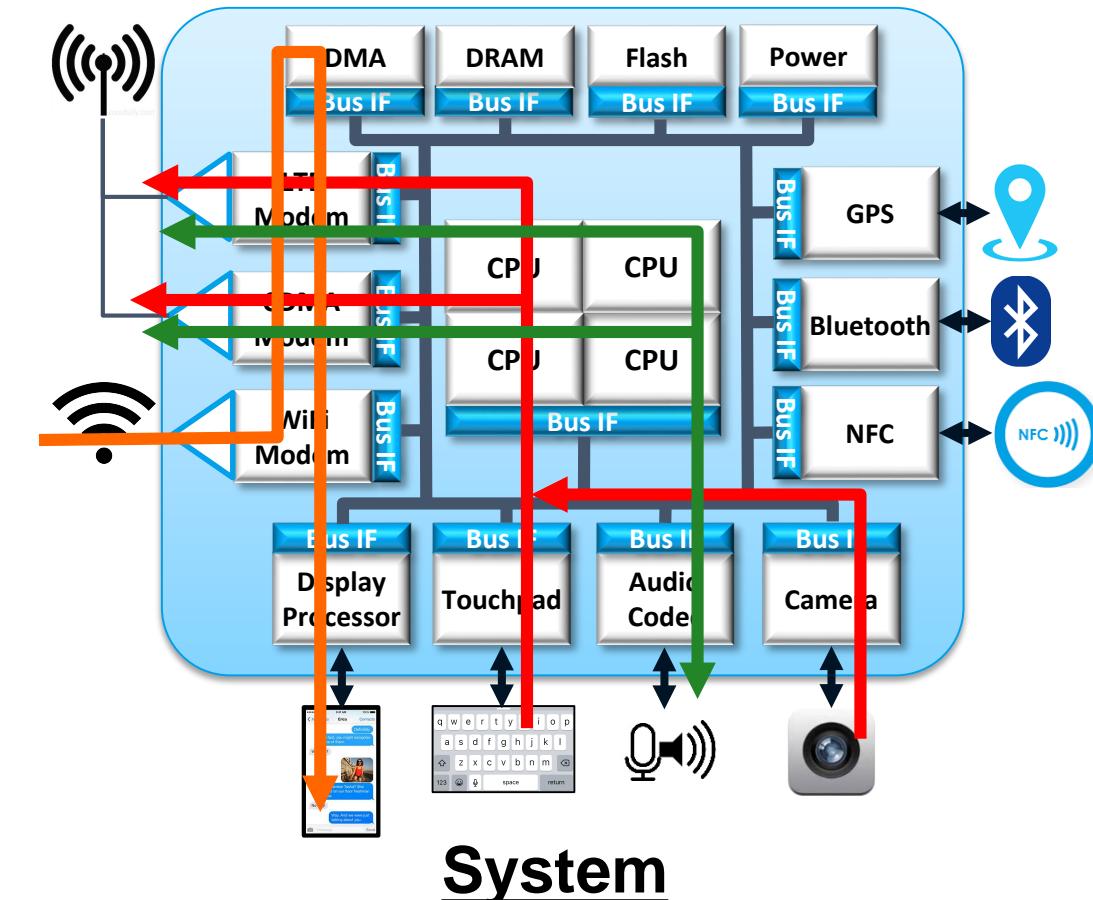
Block

Subsystem

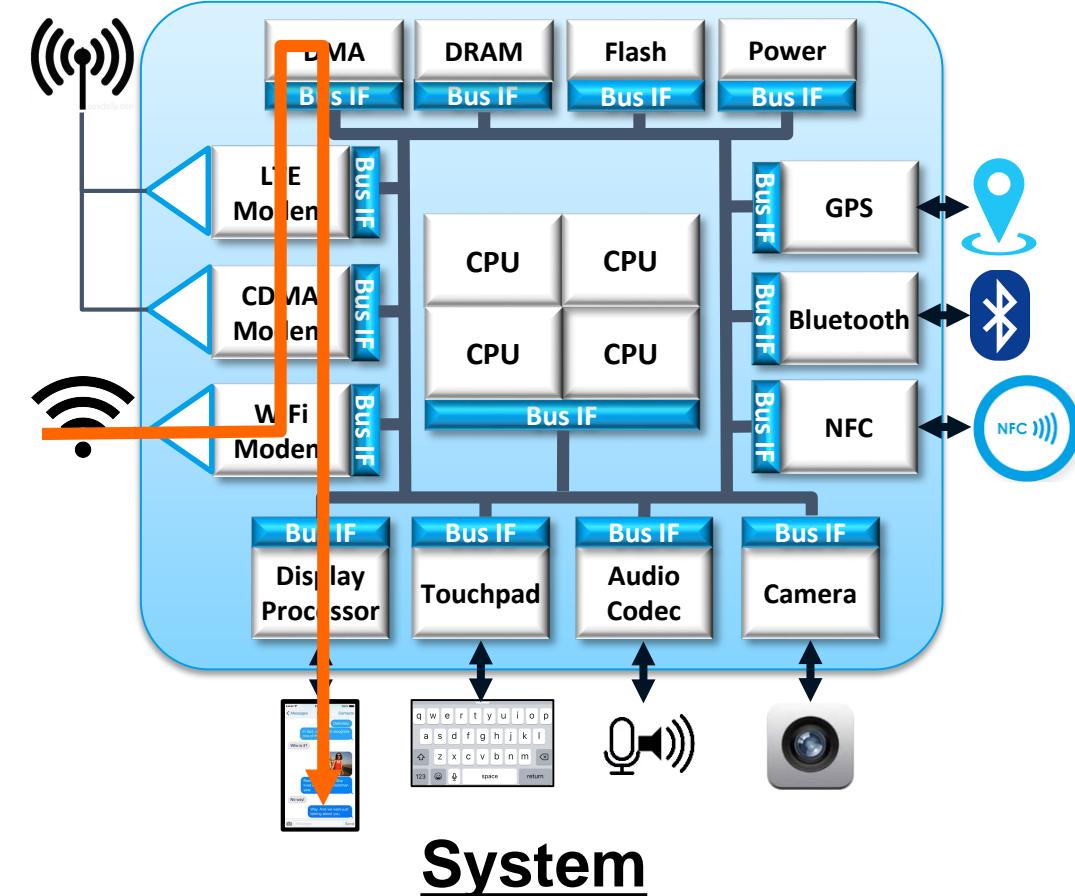
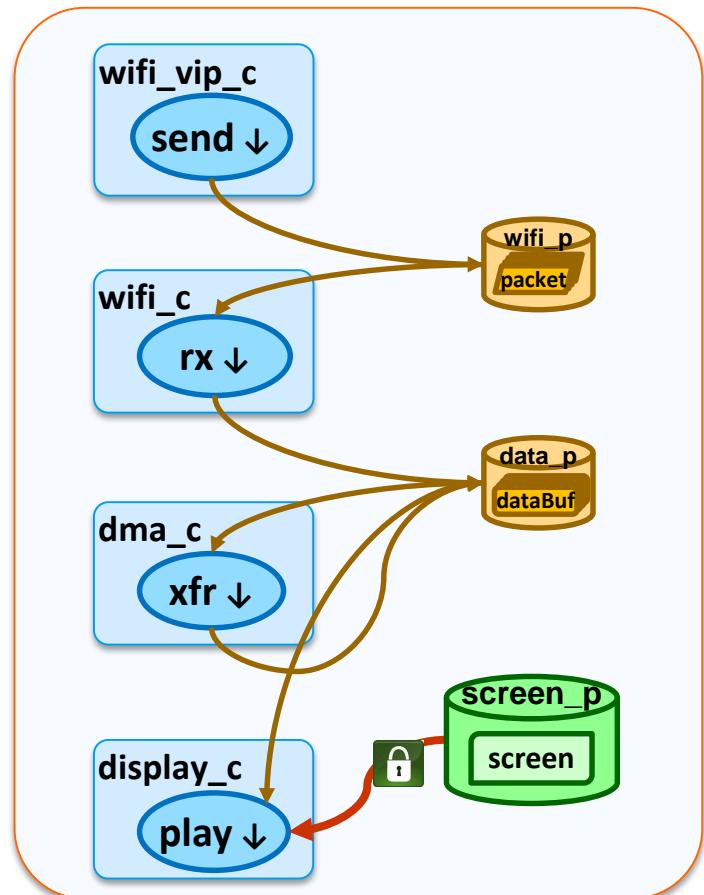
System

Full System Scenarios

- Reuse Sub-System Voice Call model
- Add Streaming Video over Wifi
- Add Text Message with Photo



Streaming Video over Wifi



Streaming Video over Wifi

```

class screen : public resource {...};

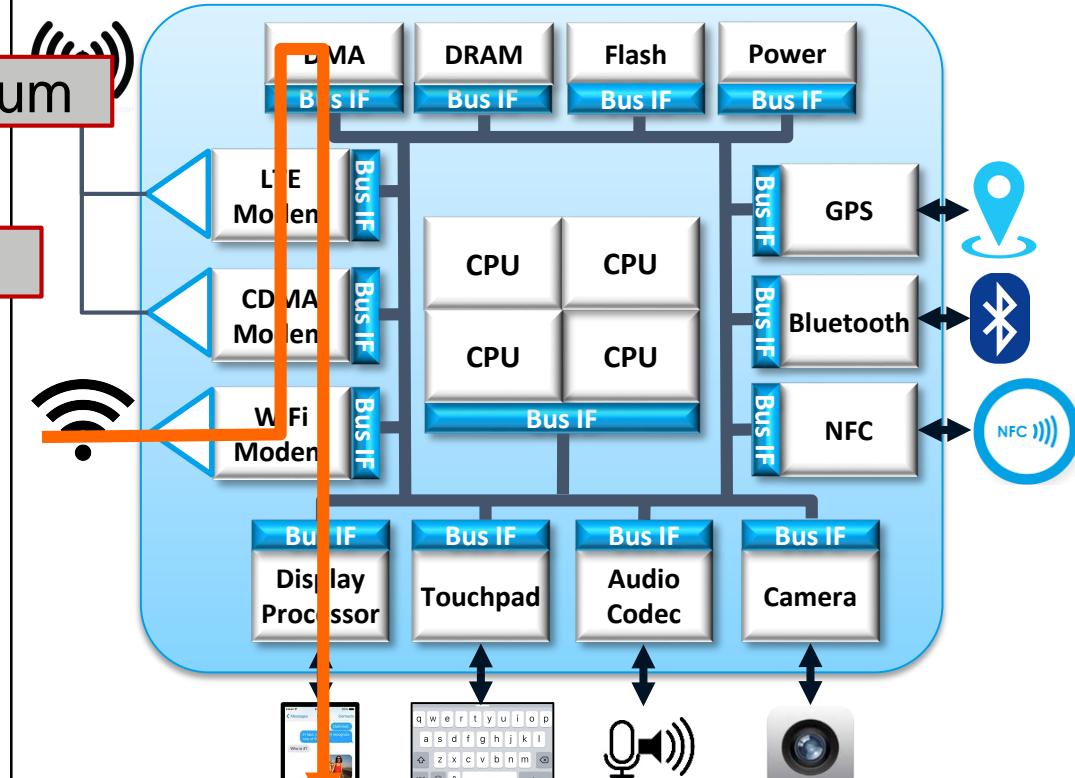
declare randomizable enum
constructor macro
random attribute

class display_c : public component {
PSS_CTOR(display_c, component);

class play_a : public action
constraint
PSS_CTOR(play_a, action) lock resource
input <datBuf> data{"data"};
constraint c {data-> declare type };
lock <screen> 1k {"1k"};
...};
type_decl<play_a> play_d;
};

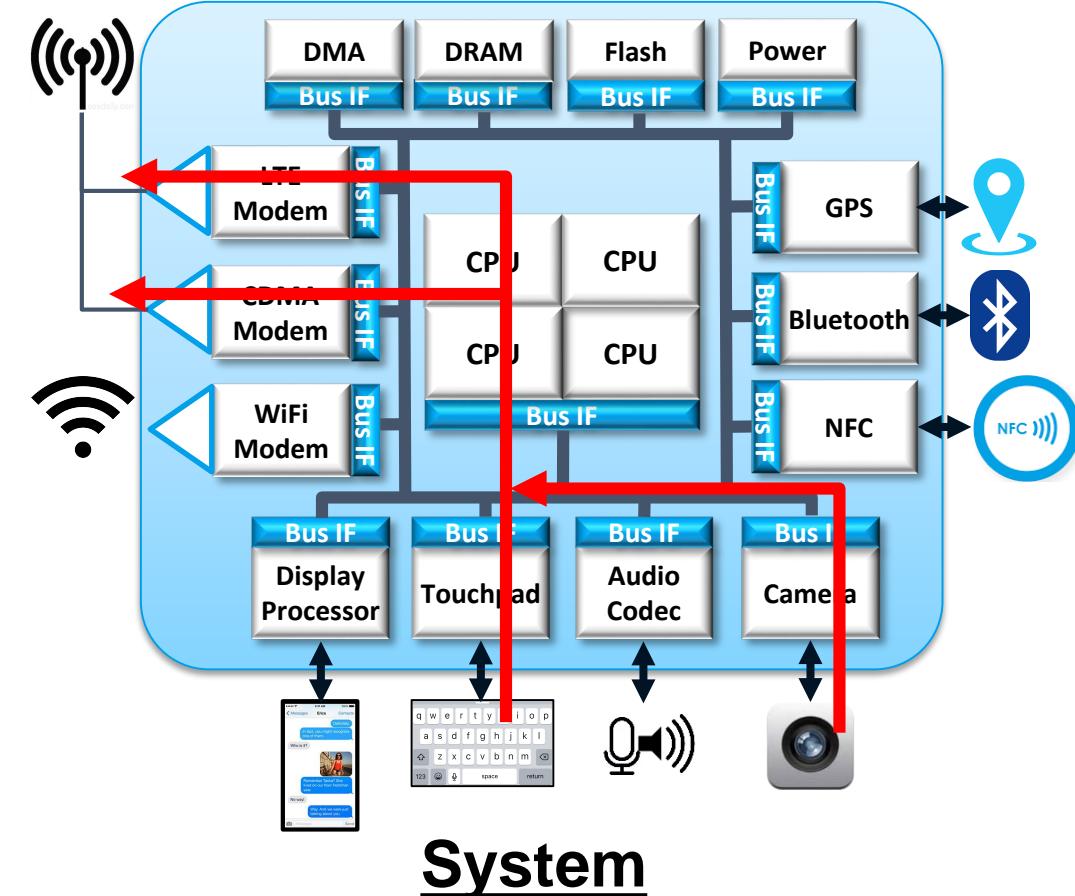
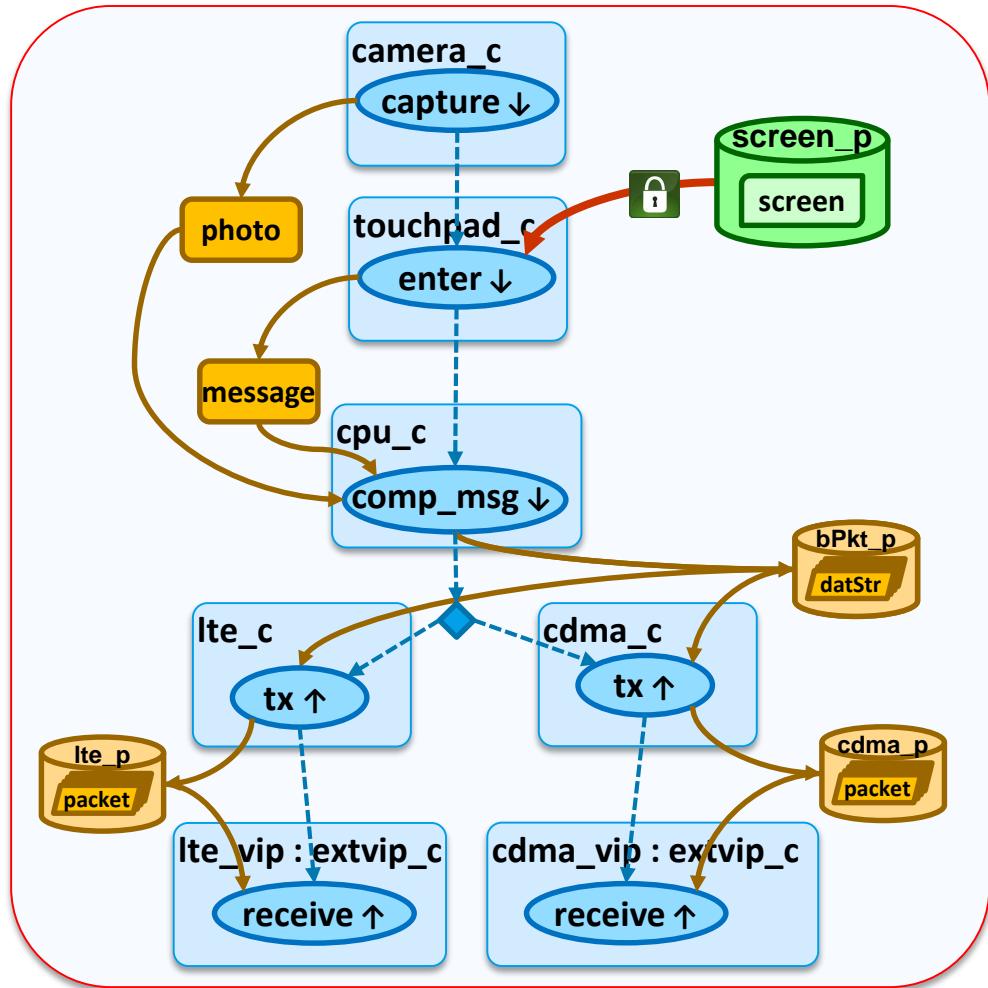
type_decl<display_c> display_d;

```



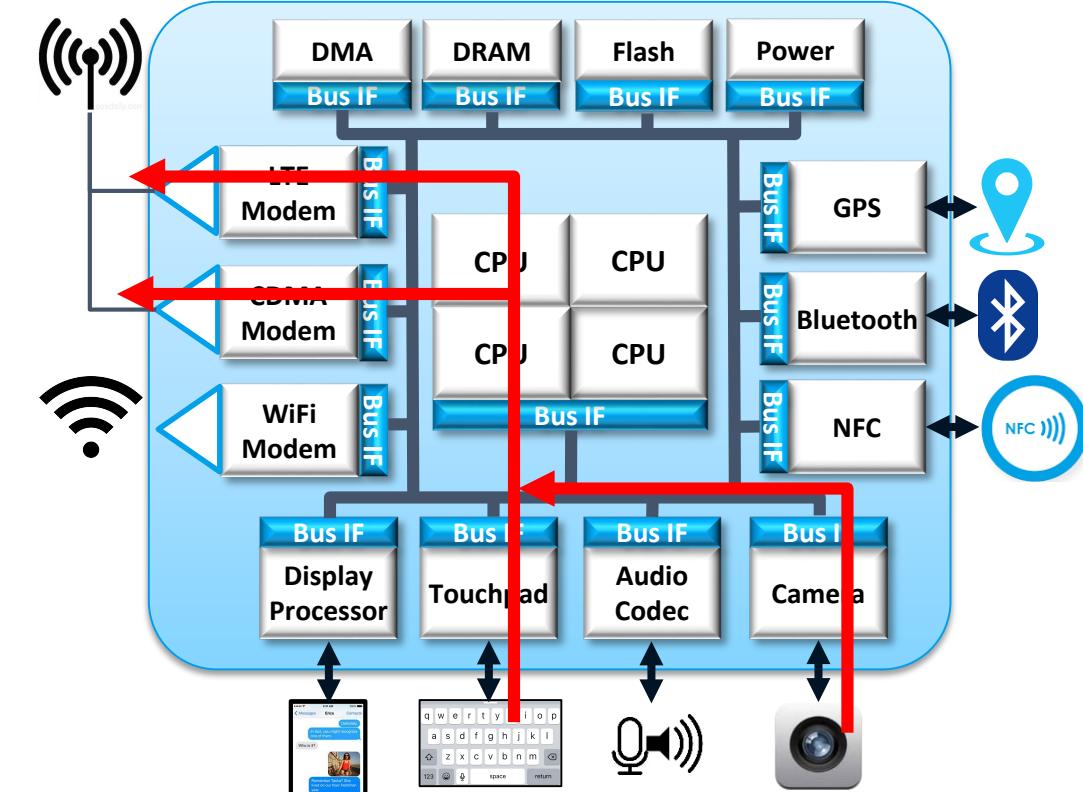
System

Text Message with Photo



Text Message with Photo

```
component touchpad_c {
    action enter_a {
        output message msg;
        lock screen 1k;
        ...
    }
}
```



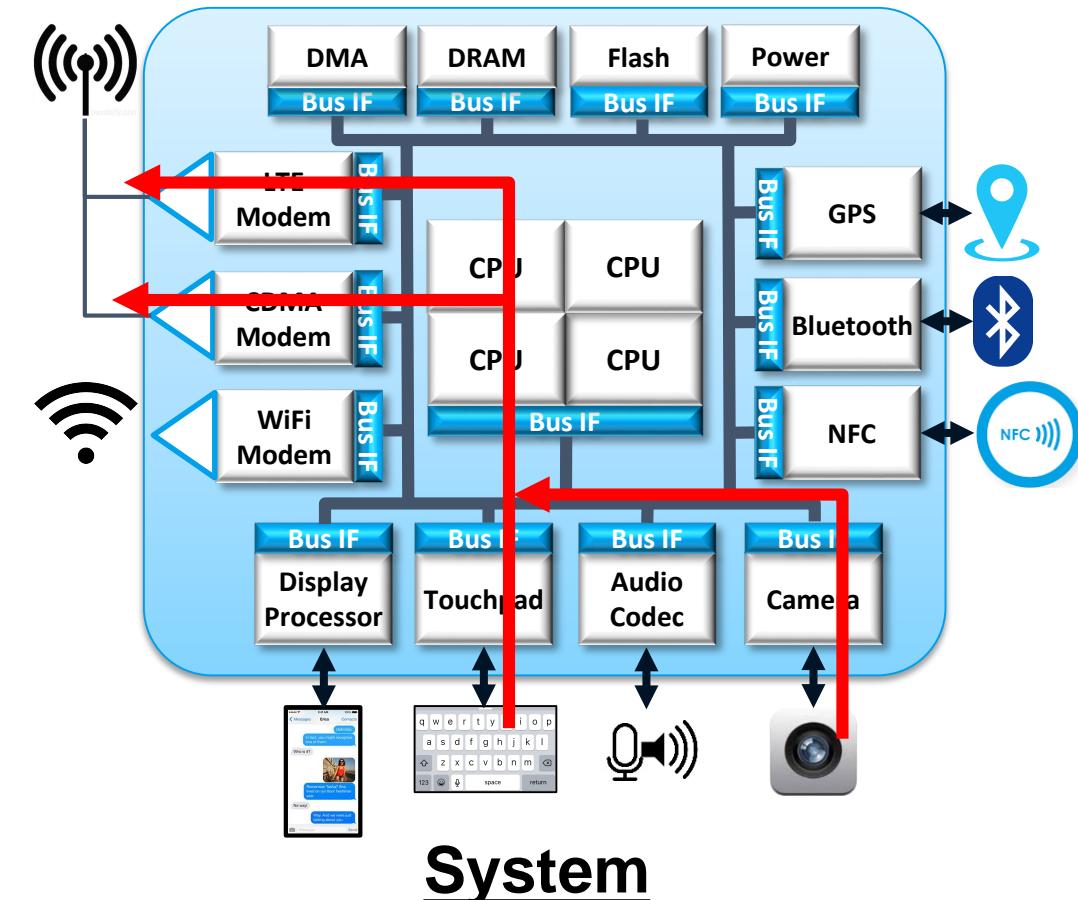
System

Text Message with Photo

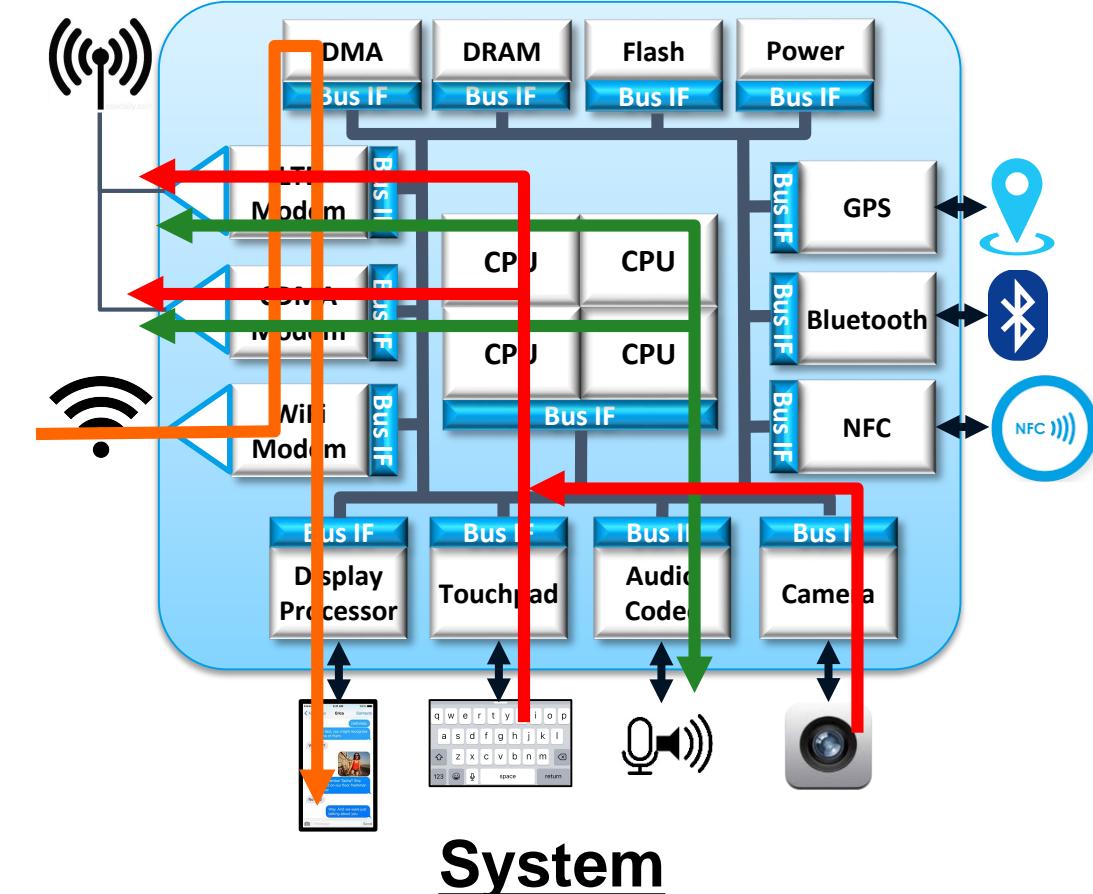
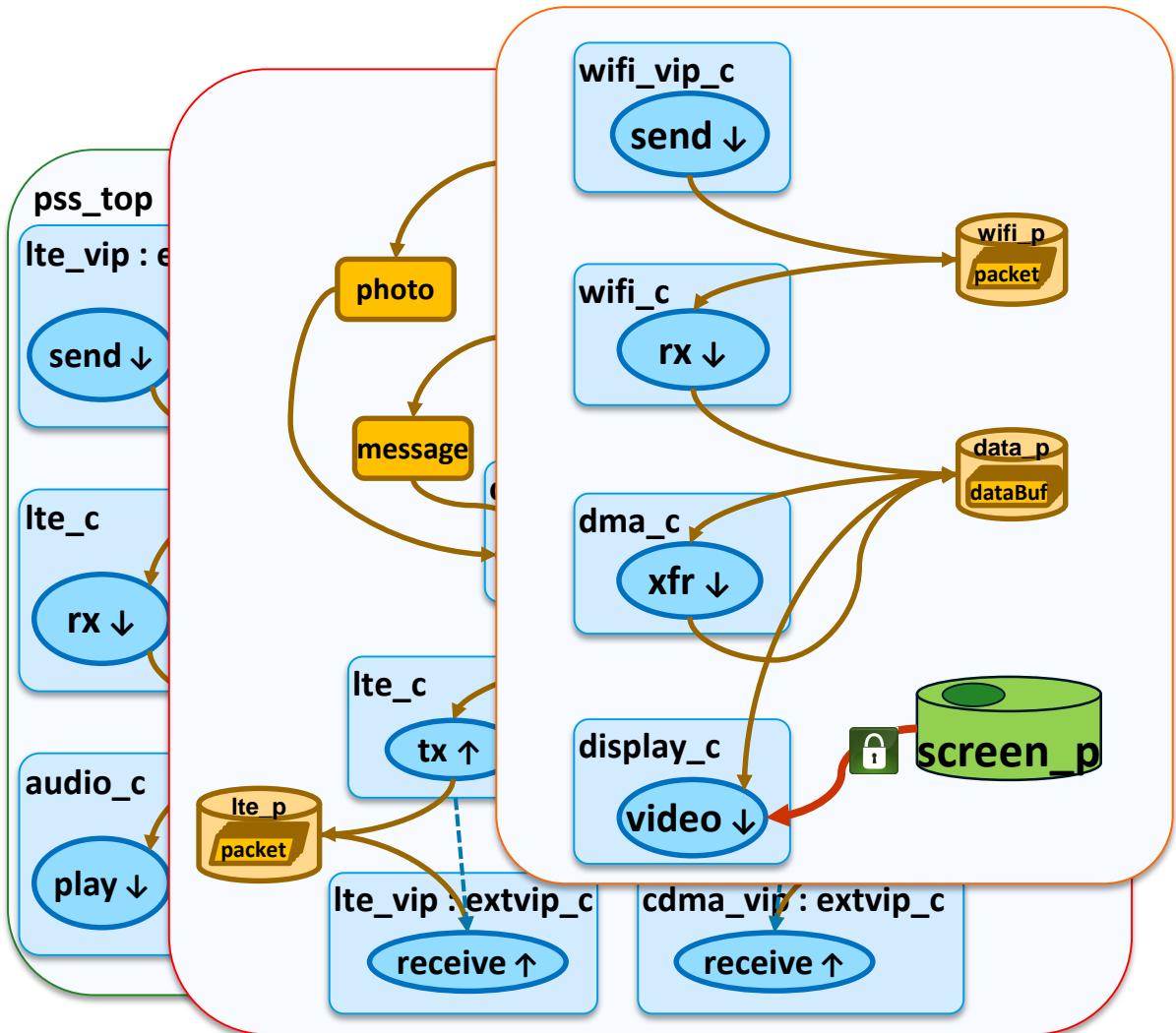
```
component pss_top {
    action txt_msg_a {
        camera_c::capture_a capture;
        touchpad_c::enter_a enter
        cpu_c::send_msg send;

        bind capture.out_photo send.in_photo;
        bind enter.out_msg send.in_msg;

        activity {
            capture;
            enter;
            send;
        }
    }
}
```



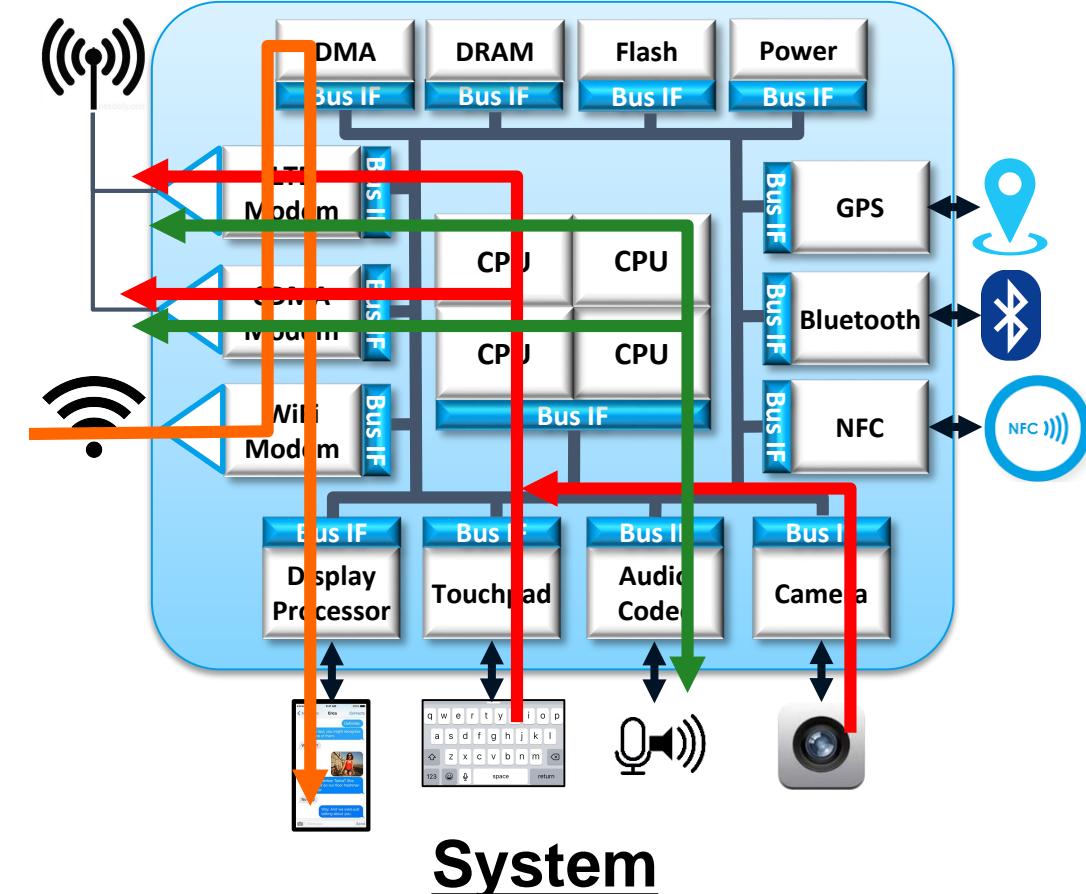
Putting it All Together



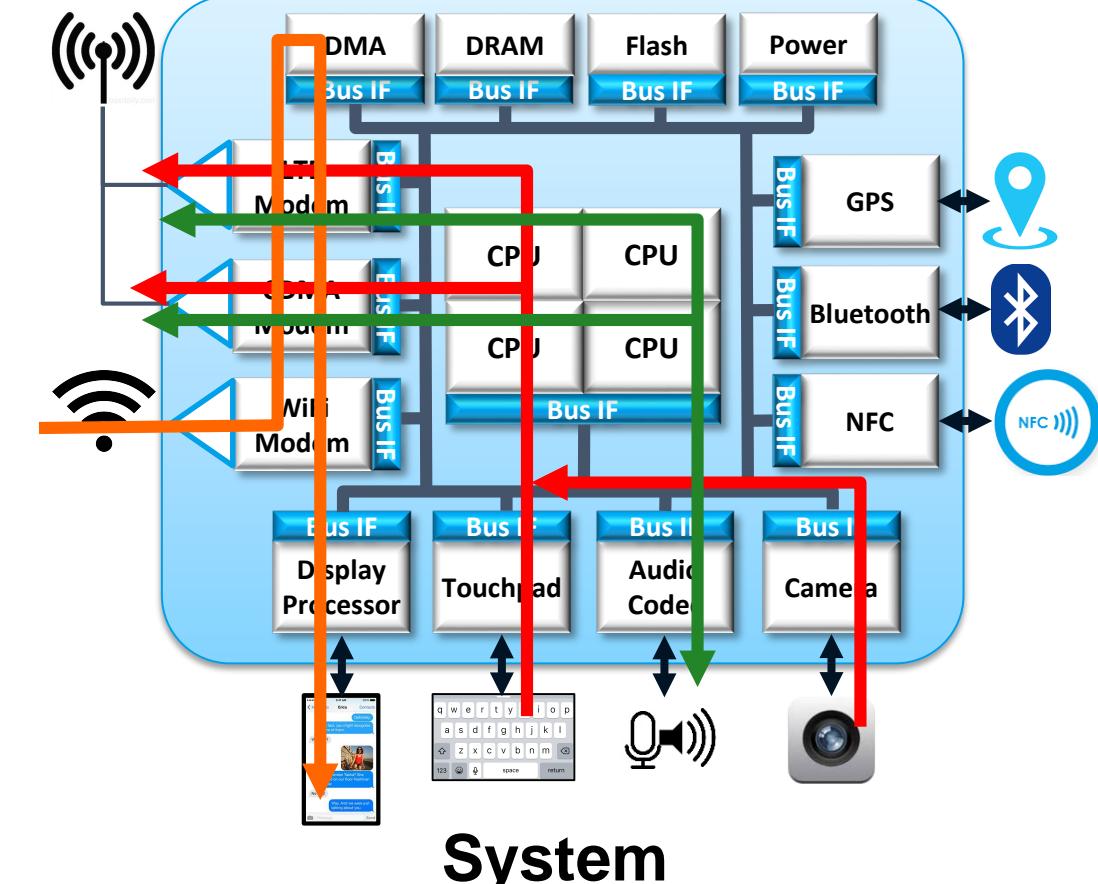
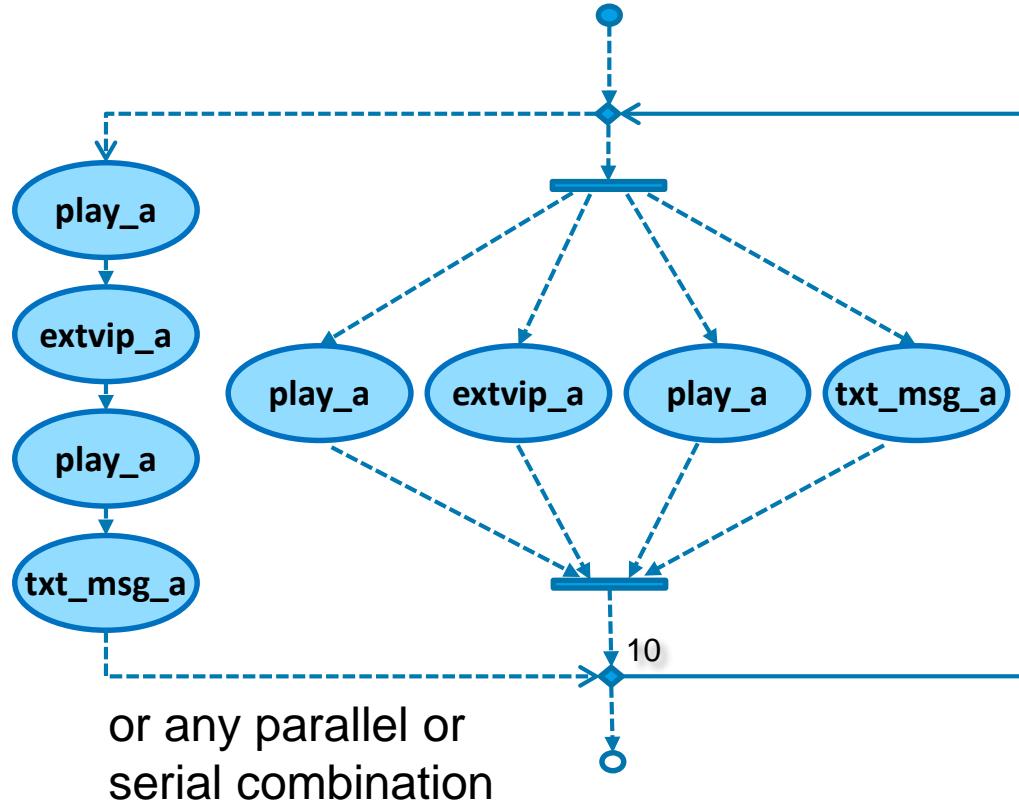
Putting it All Together

```
component pss_top {
    // imports
    // instantiations
    // pools & binds

    action test {
        activity {
            repeat (10) {
                schedule {
                    do audio_c::play_a;
                    do extvip_c::receive;
                    do display_c::play_a;
                    do txt_msg_a;
                }
            }
        }
    }
}
```



Putting it All Together



Thank You!

Portable Test and Stimulus: The Next Level of Verification Productivity is Here

Part 3: Panel Discussion

Accellera Portable Stimulus Working Group

Introducing the Panel

- Faris Khundakjie, Intel, PSWG Chair
- Sharon Rosenberg, Cadence
- Srivatsa Vasudevan, Synopsys
- Karthick Gururaj, Vayavya
- Tom Fitzpatrick, Mentor
- Adnan Hamid, Breker

Moderator: Larry Melling, Cadence

Enhancements Being Worked For 1.0

- Enhanced control of random selection and scheduling of actions
- Enhanced coverage constructs for coverage of flows, action scheduling, and resource utilization
- Enhanced features to handle hardware-software interface and product-configurable features
- Enhanced modeling of memory management
- Enhanced type system to include additional array types and parameterization by type and value
- Enhanced reactivity of model to environment
- Enhanced conditional code processing

Thank You!